

MANUAL
Classic P3
1QuadrantThyristorDrive

15to40A



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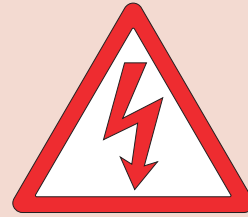
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1 Basic-Information

Electronic equipment is not fault proof. This fact should be borne in mind for all possible operating conditions.

ATTENTION Highvoltage

360/550VAC,450/550VDC



Before installation or commissioning begins, this manual must be thoroughly read and understood by the technical staff involved.

If any uncertainty arises, the manufacturer or dealer should be contacted.

P3 devices are power electric parts used for regulating energy flow.

Protection rating IP00.

Standards and guidelines

The device and its associated components can only be installed and switched on where the local regulations and technical standards have been strictly adhered to:

EU Guidelines	89/392/EWG, 84/528/EWG, 86/663/EWG, 72/23/EWG EN60204, EN50178, EN60439-1, EN60146, EN61800-3
IEC/UL	IEC364, IEC 664, UL508C, UL840
VDE Regulations	VDE100, VDE110, VDE160
TÜV Regulations	

Trade body guidelines VGB4

The user must ensure that in the event of:

- device failure
- incorrect operation
- loss of regulation or control

the axis will be safely de-activated.

It must also be ensured that the machine or equipment are fitted with device independent monitoring and safety features.

Setting adjustments

- should only be carried out by suitably trained personnel
- should only be carried out in accordance with health and safety guidelines

Assembly

- should only be carried out when all voltages have been removed.

QS

Test results are archived with the device serial number by the manufacturer.

CE

The device adheres to the following: Guideline EU 89/336/EWG. EMC standards EN61000-2 and EN61000-4.

Attention

This device description MANUAL P3 only describes the basic control unit and it must be read in conjunction with a control manual (e.g. REG).

The following control units for 1 quadrant control are available:
analogue control REG



General information

In conjunction with a control board (e.g. REG) the Classic P3 range of thyristor drives act as current controllers (moment of inertia controllers).
A 26-pin connector, common to all boards, is used to connect the power section and the control electronics. Using this interface it is possible for any external control arrangement including third party equipment to drive the power section.

P3 drives are used to control the speed, the voltage or the moment of inertia of dc motors.

1 Basic-Information

Build

- switch cabinet mounting according to the VDE, DIN and EU regulations
- standard control electronics REG
- intrinsically safe power section with current control loop
- optional units

Galvanic isolation between

- the power section and the housing
- the power section and the control electronics

The distance of air gaps and leakage paths adhere to the VDE standards (>8mm).

Components

- fully insulated thyristor modules, comfortably over-dimensioned
- only components customary in trade and industrially standardised are used
- high-quality bases for the IC with external connections
- LED displays
- DIP switches for the P-I adjustment of the current control loop
- precision potentiometers for fine adjustments
- plug-in jumpers for the system set-up

Characteristics Series Classic P3

- * Thyristor drive for dc motors
- * Power range 6.75kW to 22kW
- * Drive in the first quadrant
- * Energy recovery
- * Intrinsically safe power section
- * Completely controlled three-phase bridge circuit as output stage
- * Fast analogue current control
- * 26-pin interface
- * Features of the control electronics:
see Manual REG or third-party product documentation
- * Optional units

P3400/450-x

Power connection 360-440V~
 Auxiliary voltage connection 360-440V~, 200-250V~
 Output voltage max. +450V=
 Cooling self cooling

P3400/450-		15	25	40
Input current	A~	12	20	32
Output current peak	A=	30	50	80
continuous	A=	15	25	40
El. power	kW	6,75	11,25	18
Input fuses (fast acting) Input	AFF	20	30	50
Mains chokes	Typ mH	KD2-16 0.9	KD2,5-25 0.7	KD2,5-50 0.4
Armature chokes	Typ mH	EI135A-16 33	EI135B-24 16	EI150B-35 8
Dimensions h x w x d	mm	200x160x110	200x160x127	240x160x127

P3500/550-x

Power connection 500-550V~
 Auxiliary connection 360-440V~, 200-250V~
 Output voltage max. + 550V=
 Cooling self cooling

P3500/550-		15	25	40
Input current	A~	12	20	32
Output current peak	A=	30	50	80
continuous	A=	15	25	40
El. power	kW	8,25	13,5	22
Input fuses (fast acting) Input	AFF	20	30	50
Mains chokes	Typ mH	KD2-16 1,2	KD2,5-25 0,7	KD2,5-50 0,5
Armature chokes	Typ mH	EI135A-16 33	EI135B-24 16	EI150B-35 8
Dimensions h x w x d	mm	200x160x112	200x160x127 7	240x160x127

1 Basic-Information

Specification

Mains frequency	50 or 60Hz $\pm 5\%$
Protection rating	IP 00
Format	VDE 0100 group C, VDE 0160
Humidity rating	class F acc. to DIN 40040
Site of installation	< 1000m above sea level
Operating temperature range	0 ... 45°C
Extended operating temp. range	up to 60°C reduced by 2%/°C
Storage temperature range	-30°C to + 80°C

Amplification

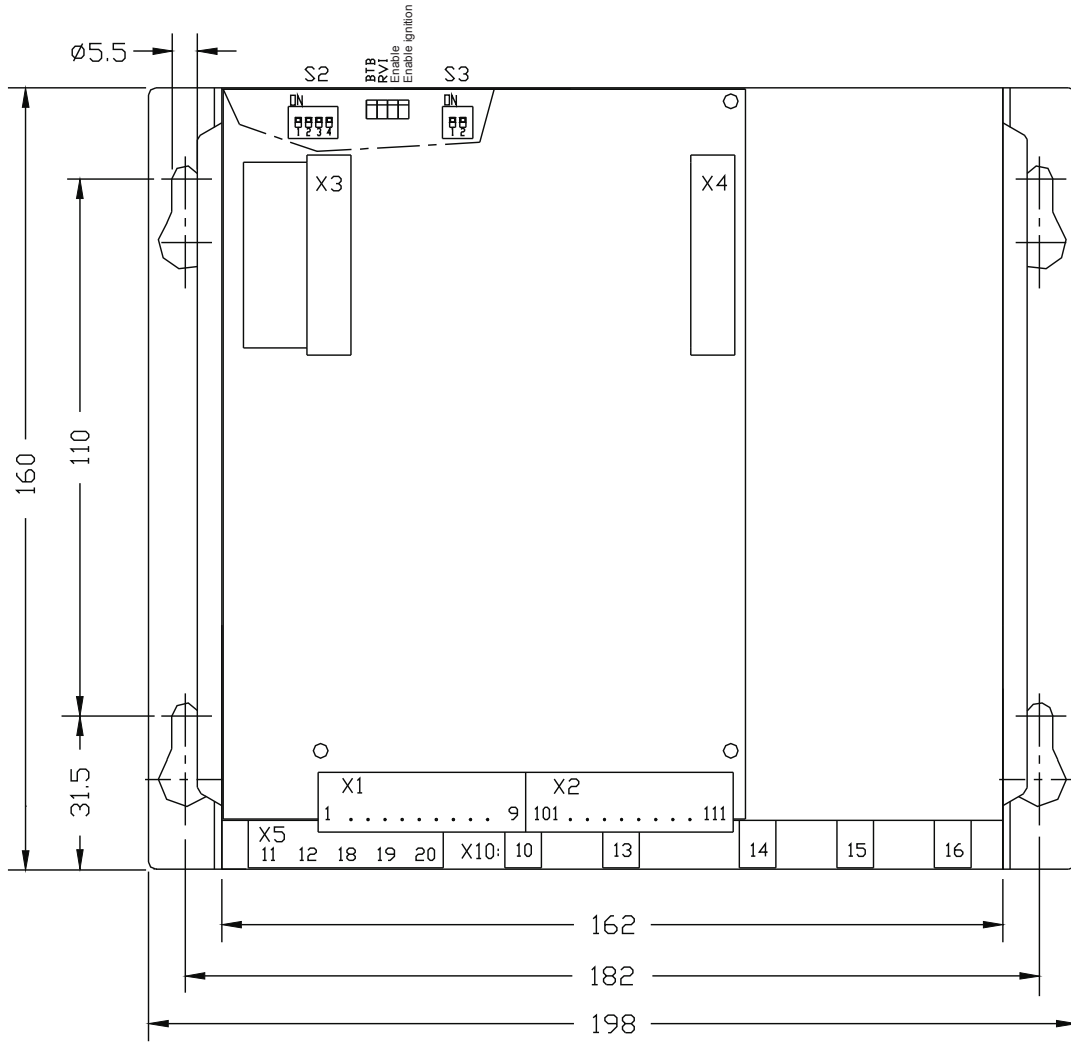
- input signal	0 to $\pm 10V=$
- output	0 to $\pm 200\%$ type current
Enable	+10V
Current control loop circuit	
- control precision	$\pm 2\%$
- control range	1:50
Speed control loop circuit with REG	
- control precision (without actual value error)	$\pm 0.1\%$
- control range	1:300

InterfacecontrolelectronicsX3

Function		Connectorno.
+ 24V	$\pm 10\%$	X3: 1 and 2
+15V	$\pm 2\%$	X3:3and4
-24V	$\pm 10\%$	X3:5and6
-15V	$\pm 2\%$	X3:7and8
DeviceGND		X3:9,10,11,12,13,14
commandvalue(GND)	0	X3:15
lcommandvalue(signal)	+10V=	X3:16
Currentcontrollerenable	+10V=	X3:17
Drivedisable1	+10V=	X3:18
Drivedisable2	+10V=	X3:19
N(speed)actual	+10V=	X3:20
I(current)actual	+10V=	X3:21
Over-currentpowersection	n/a	X3:22
Triggerangle1	+10V=	X3:23
Triggerangle2	+10V=	X3:24
DrivereadyBTB	+10V=	X3:25
notassigned	n/a	X3:26

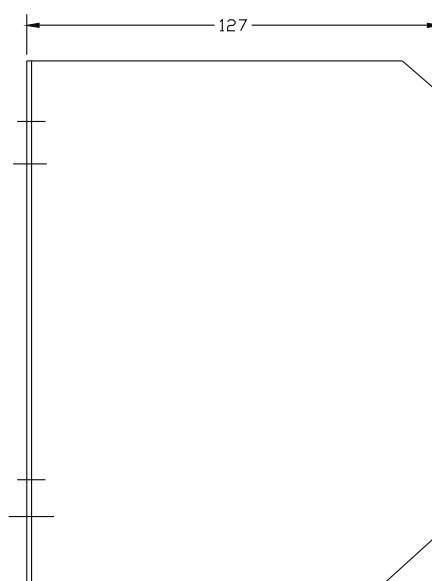
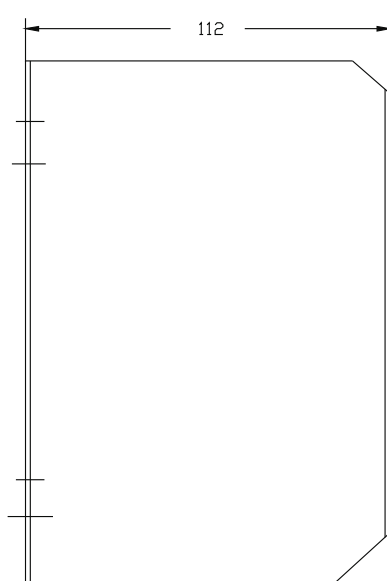
ClassicP3x/x-15-40A

Dimensions P3 15-25A

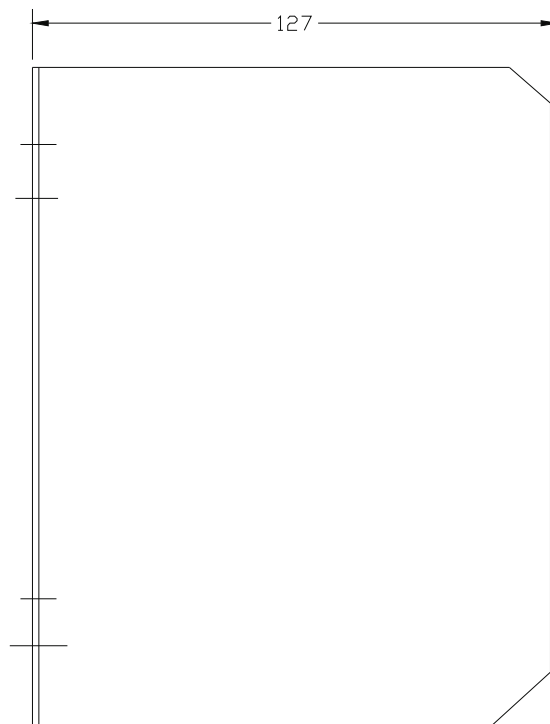
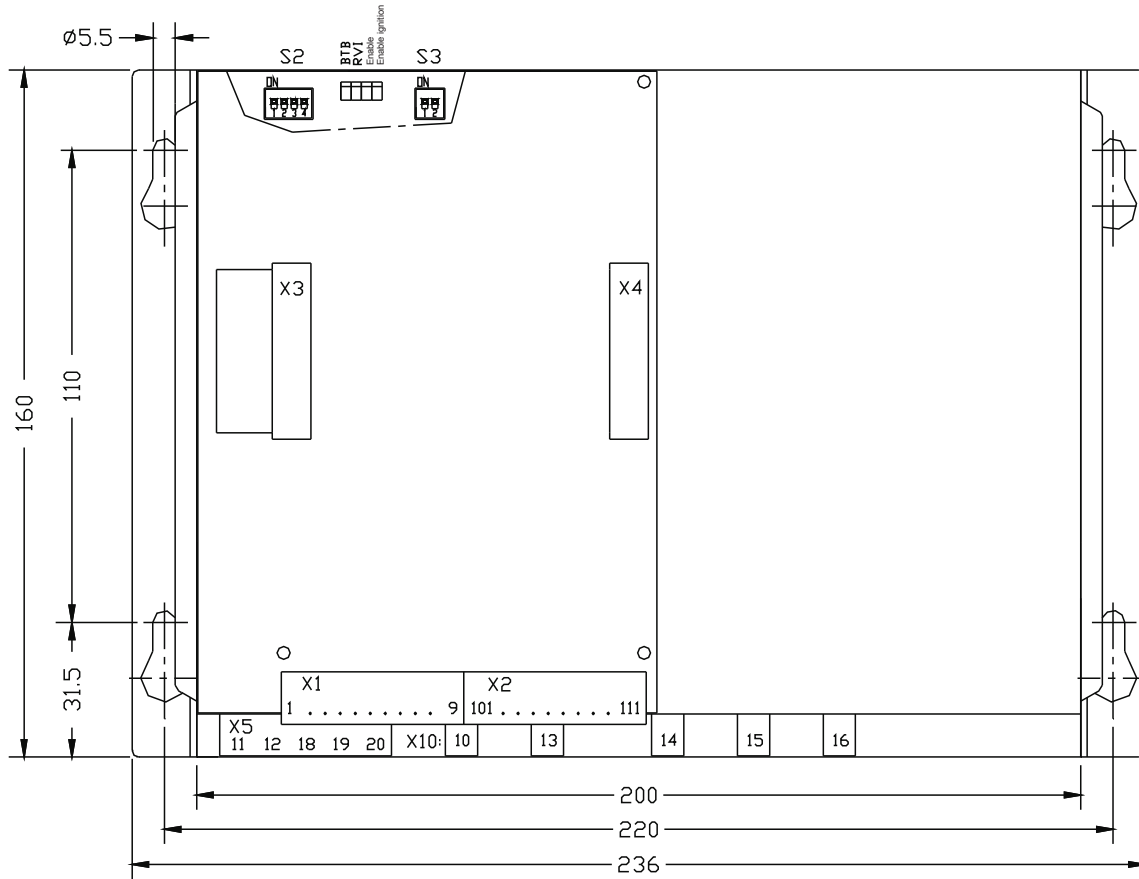


15A

25A



2 Mechanical Installation



Dimensions P3 40A

Attention:

The order of the connections to the connector numbers or screw terminals is obligatory. All further advice is non-obligatory.

The input and output conductors may be altered or supplemented in accordance with the electrical standards.

Note:

- Connectionandoperatinginstructions
- Localregulations
- EUguideline89/392/EWG,84/528/EWG,86/663/EWG
- VDEandTÜVregulationsandTradebodyguidelines
- CEadvice,EMC



Connection Conductor minimal cross-section				
Type current	A	15	25	40
ac power supply	mm ²	1.5	2.5	4
Motor line	mm ²	1.5	2.5	4
Auxiliary voltage	mm ²	0.5	0.5	0.5

3 ElektricalInstallation

Connection advice

This connection advice is a general information and non-obligatory.

Note:

- Connection and operating instructions
- Local regulations
- EU guideline 89/392/EWG
- VDE and TÜV regulations and Trade body guidelines



Switch on the auxiliary voltage and the supply voltage simultaneously.

Switch off the supply voltage after the auxiliary voltage

Input filter

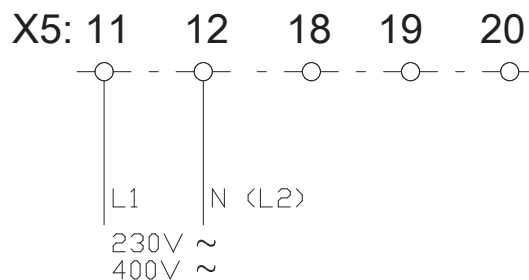
see CE advice, page 15

Short conductor length to be used between the input filter and the device

Operation with 60Hz: switch S3 contact 1 in position ON

Auxiliary voltage connection

Connection	terminal X5:11, X5:12
Power supply	230V~ or 400V~ (Pls. observe the type plate)
Input current	0.1A
Phase position	regardless
Internal fuses	2.5Af



Direct power connection

Connection

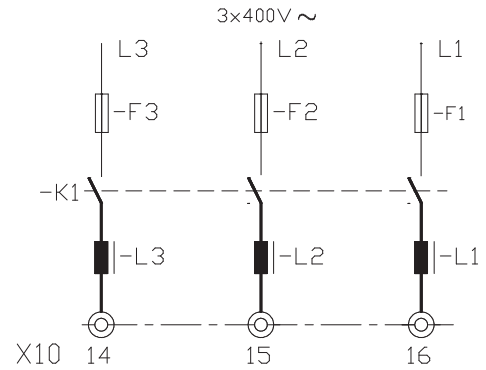
Phase	L1	terminal X10:16
Phase	L2 (N)	terminal X10:15
Phase	L3	terminal X10:14

Input fuses

Super fast acting fuses

Powerchoke

Inductance >200mH



Power connection with a transformer

Transformer performance

1.1 x continuous motor power

Secondary voltage

0.9 x motor power

Transformer fuses

Slow acting

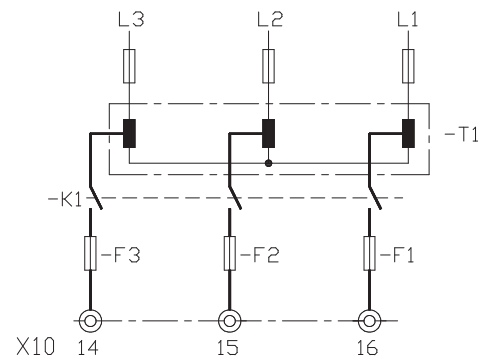
Input fuses

Super fast acting fuses

Attention:

If the secondary voltages produced by the transformer are inferior to 60% of the rated device voltage, the voltage watchdog has to be adapted. These modifications may only be effected in the factory and thus, the transformer secondary voltage has to be indicated on order.

Internal watchdog for fuse failures



3 ElektricalInstallation

Motorconnection

Connection

Motor- bolt X10:10
Motor+ bolt X10:13

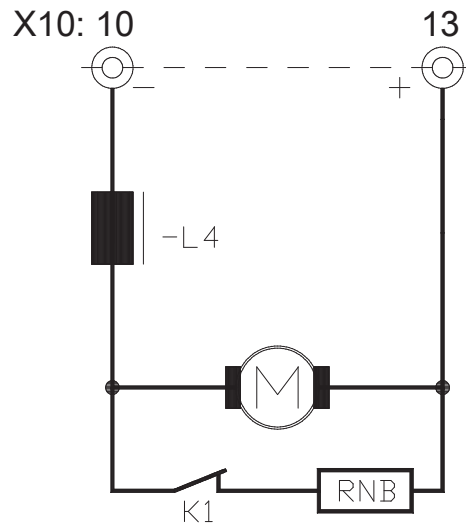
Armaturechoke

Inductance: $-L 4[mH] = U/I \cdot x 0.8$

Armature chokes are only necessary for special applications, e.g. low-noise motor operation (stagecraft).

Switchinginthearmaturecircuit

- dc circuit current-free
- disable inactive



Warning :

Faulty switching will create arcing across the switch contacts.



Powersupplyfailure-brakeresistor

Break contact of the mains contactor K1 in parallel to the motor armature without separation from the device

Attention:

Power lines have to be shielded and routed separately from control lines!



For electro-magnetic interferences please refer to the CE advice (page 15).

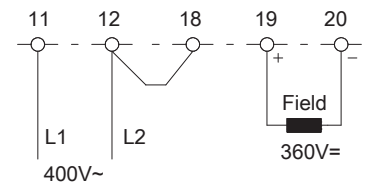
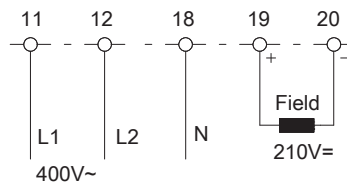
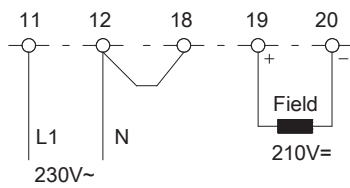
Fieldconnection

Connection

Input
 Field negative
 Field positive

Plug-interterminalconnectors

X5:11, X5:18
 X5:20
 X5:19



Fieldvoltage

Powersupply

230V~
 400V~
 400V~ with N

Fieldsupply

210V=
 360V=
 210V=

Field current

max. 1.5A

Fuses

2.5Af

Watchdog

omitted

3 Elektrical Installation

CE Advice

The devices adhere to the EU guidelines 89/336/EWG and the technical standards EN 61000-2 and 61000-4 provided that the following conditions are observed:

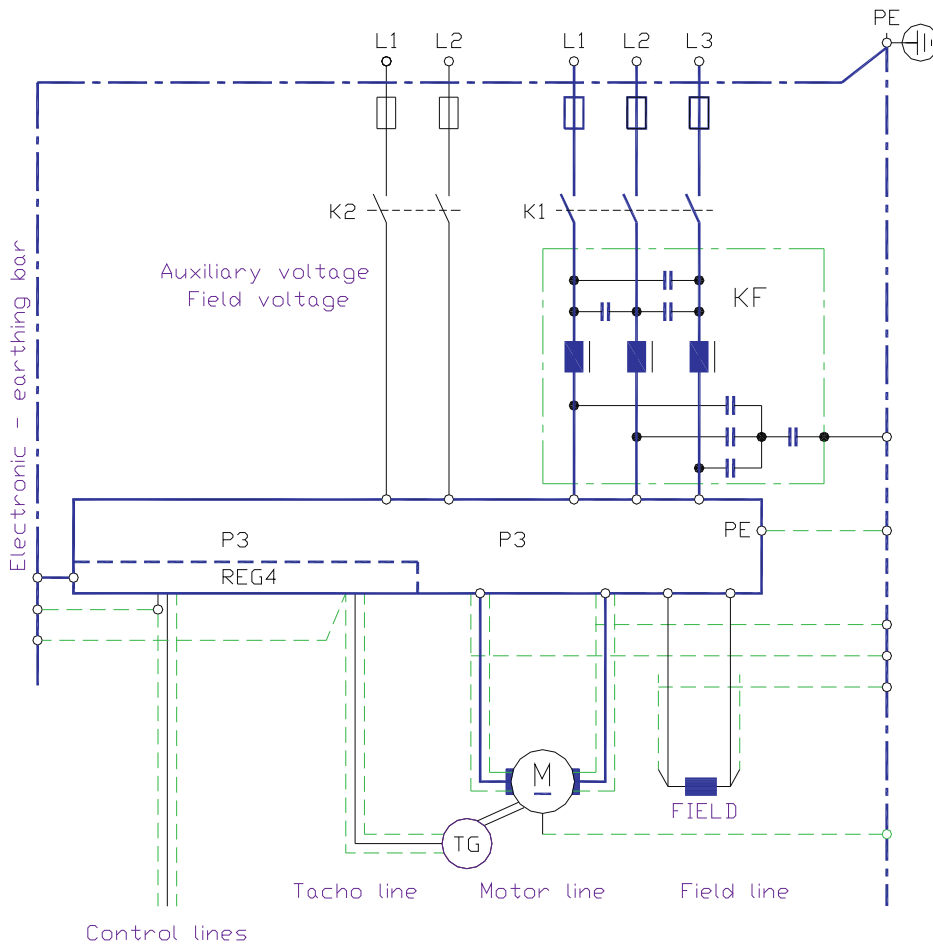
- The device, the power choke, and the filter capacitors are mounted on a 500x500x2 mm mounting plate.
- The mounting plate must be connected to ground using a 10mm² wire.
- The motor housing must be connected to ground using a 10mm² wire.
- The device ground X1:8 must be connected to the mounting plate using a 2.5mm² wire.
- Device PE screw must be connected to the mounting plate using a 4mm² wire, l = 50mm.

Connection:

Power choke type: see technical details

Filter capacitors: 3 x 0.5 μF/600V ~ 3 x 1 μF (x) + 1 x 0.5 μF (y)

Conductor length between the device and the power choke <250mm



KF = Commutation choke with filter capacitor

Actual value connection

Tacho

Suitable actual value encoders:

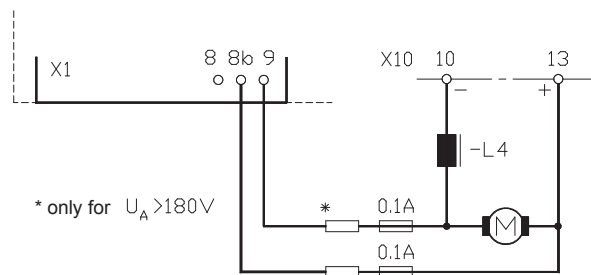
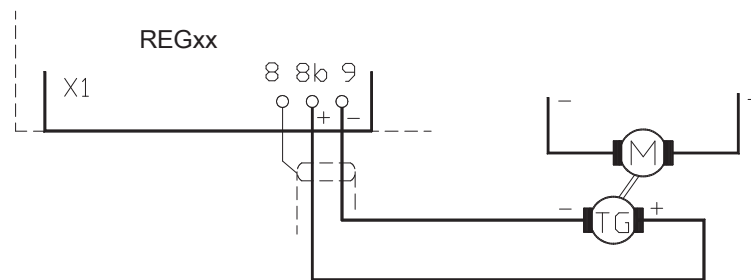
- DC tacho generator
- Brushless tacho generator with evaluation electronics
- Incremental encoders with evaluation electronics
- AC or three-phase tacho with rectification

Connection

Control electronics (see Manual REG)

In case of a positive command value

Tacho positive	X 1:8b
Tacho negative	X 1:9
Shield	X 1:8



Armature voltage

Ground referenced actual value

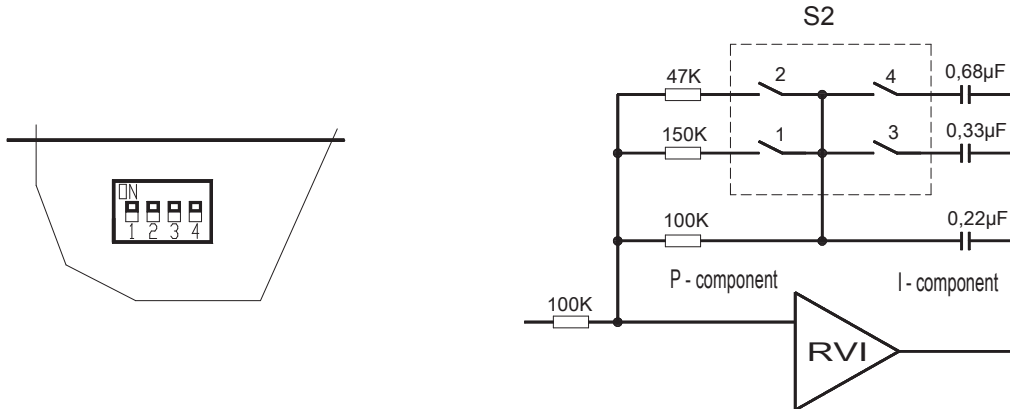
Fuses	2x 0.1A/500V	directly in the armature circuit
For armature voltage	>180V=	additional resistors are required
Use unit	EXZU-UA1	
(including 2 fuses and 2 resistors in an insulated housing)		

4 Adjustment

Adjustments- Currentcontroller

Currentcontroller-Pi loopcircuit

Adjustments with the DIP switch S2



Optimizationofthecurrentcontroller

- Connect an oscilloscope across the current actual value X3:21
- Current command value step-change 1V X3:16
- Increase the current command value by 1V steps to 10V
- Alter the P-amplification by means of the DIP switches S2:1 and S2:2
- Optimal adjustment see fig. 1
- Not permissible adjustment see fig. 2
- Alter the integral part by means of the DIP switches S2:3 and S2:4

Oscilloscope-Currentadjustment

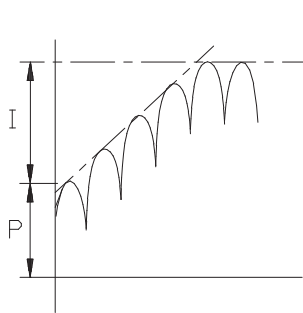


Fig. 1

Optimal adjustment

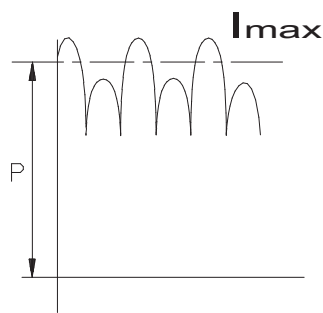


Fig. 2

Amplification too high

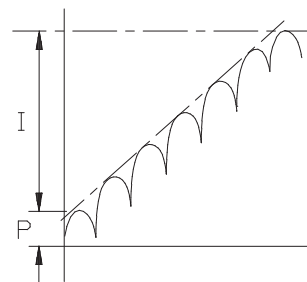


Fig. 3

P-amplification too low

Displays

Some important functions are indicated by LEDs:

Display	LED
Drive ready	BTB
Current controller enable	enable
Triggering enabled	enable triggering
Current command value direction	RVI

The green LEDs indicate the active states!

BTBsignal-Driveready

BTB signal	X3:25	>+10V
Error	X3:25	<+2V

Error

Auxiliary voltage supply +24V, +15V, -15V

Powersupply:

- Fuse failure
- Under-voltage

In case of errors or failure the power section is internally disabled without delay.

Measurements

Measurement advice

Measuring instruments: multimeters for current and voltage
shunt or clamp-on ammeter

Measuring faults: mean value > actual value
acc. to the form factor
approx. 1 to 5%

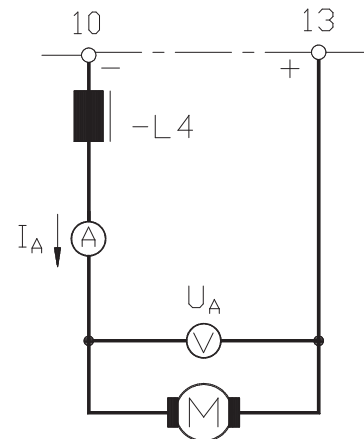
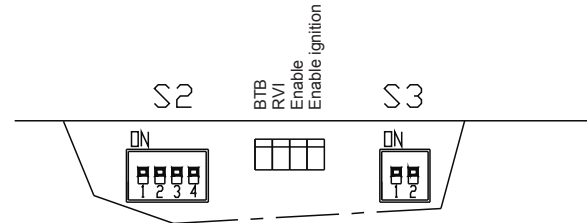
Measured values

with a positive command value

Voltage: X10:10 negative, X10:13 positive
max. 1.15 x power supply
Current: ammeter in the motor circuit

Measured values across REG4

Speed	X2:109	±5V	for ±100% speed
Current	X2:111	±5V	for ±200% current
GND	X2:104		



5 Commissioning

Commissioning

1. Connection advice

Connect the drive in accordance with the P3 manual and the control electronics manual (e.g. REG).

Please observe in particular:

- Check the power supply voltage with that specified on the type plate.
- Insert the correct fuses according to the technical data (rf. to page 6)
- Check the field voltage connection and the motor and tacho connections!
- For 60Hz applications set the switch S3, contact 1 to ON

2. Commissioning

Basic connections:

Mains supply, field, tacho, or armature feedback, drive enable, command value.
For armature voltage control the tacho watchdog must be switched off.

2.1 Drive enable switch	open or drive enable voltage	0V
Command value		0V
Switch S9		adjust to tacho voltage
for armature voltage control		adjust to 0
Switch S4		position 2
Switch S5		position 6
Potentiometer I _{max1}		left full scale
Potentiometer I _{max2}		adjust to approx. 10% of full scale
Potentiometer	XP	adjust to 50%
Potentiometer	ID	= 10
Potentiometer	IxR	= left full scale
Potentiometer	n _{max}	= left full scale
Potentiometer	INT	= left full scale

2.2 Apply the voltage

The LEDs L3 (BTB) and L7 (stationary) **must** light.
All other LEDs are off.

2.3 Close the switch 'drive enable' or apply drive enable voltage of 10V

The LEDs L1 and L2 must also light

The drive must be at a standstill or turn slowly (offset).

If the drive accelerates in the correct direction, the polarity of the tacho voltage and the armature voltage feedback must be changed.

If the drive accelerates in the wrong direction, the polarity of the armature or the field must be changed.

2.4 Increase the command value voltage to approx. 10%

The drive must accelerate to approx. 10% of the speed.

If the rotation direction is wrong, change the polarity of the tacho and the field or the polarity of the tacho and the armature.

2.5 Current controller amplification

(Switch S2 on the power section)

The current amplification is adjusted to a low armature circuit inductance

(all switches On)

High inductance values can lead to motor oscillation which cannot be influenced by means of the speed controller.

In this case, first set switch S2-2 to Off.

If the drive still does not run smoothly, set the switch S2-1 to Off.

The current response can be measured by means of an oscilloscope across the test point X4:20 (see page 17).

2.6 Speed controller amplification

Adjust on the REG board.

Adjust the P-term to the lowest possible setting from 1 to 5 (switch S4).

Adjust the I-term to match the axis momentum (switch S5):

large axis momentum -	high adjusted value
small axis momentum -	low adjusted value

With the command value set to 10% speed, increase the amplification by turning the potentiometer Xp clockwise. When the drive begins to oscillate, reduce the amplification by turning the potentiometer anti-clockwise by approximately 10%.

For the fine adjustment of the amplification the control response should be measured by means of an oscilloscope across the test point X4:15.

2.7 Further adjustments

such as speed, peak current, continuous current, etc.
(rf. to the manual REG and P3)

2.8 Switching Off

If the switch drive enable is opened, or the drive enable voltage is switched to 0V, LED L1 and L2 will extinguish and the drive will be disabled.

DIP switch DS1:K4 (REG4) in position OFF!

After approx. 2s the thyristor triggering circuit is disabled.

2.9 Commissioning adjustments

The adjustments should be documented in the protocol and the adjustment potentiometers should be sealed with a suitable lacquer.

6 Quarantee

We guarantee that the device is free from material and production defects. Test results are recorded and archived with the serial number.

The guarantee time begins from the time the device is shipped, and lasts one year. WE undertakes no guarantee for devices which have been modified for special applications.

During the warranty period, we will, at its option, either repair or replace products that prove to be defective, this includes guaranteed functional attributes. We specifically disclaim the implied warranties or merchantability and fitness for a particular purpose. For warranty service or repair, this product must be returned to a service facility designated by us.

For products returned to us for warranty service, the Buyer shall prepay shipping charges to us and we shall pay shipping charges to return the product to the Buyer.

However, the Buyer shall pay all shipping charges, duties, and taxes for products returned to us from another country.

The foregoing warranty shall not apply to defects resulting from:

- * improper or inadequate repairs effected by the Buyer or a third party,
- * non-observance of the manual which is included in all consignments,
- * non-observance of the electrical standards and regulations
- * improper maintenance
- * acts of nature

All further claims on transformation, diminution, and replacement of any kind of damage, especially damage, which does not affect our device, cannot be considered. Follow-on damage within the machine or system, which may arise due to malfunction or defect in the device cannot be claimed.

This limitation does not affect the product liability laws as applied in the place of manufacture (i. e. Germany).

We reserve the right to change any information included in this MANUAL.

All connection circuitry described is meant for general information purposes and is not mandatory.

The local legal regulations, and those of the Standards Authorities have to be adhered to. We do not assume any liability, expressively or inherently, for the information contained in this MANUAL, for the functioning of the device or its suitability for any specific application.

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Copying, modifying and translations lie outside our liability and thus are not prohibited. Our products are not authorised for use as critical components in the life support devices or systems without express written approval.

The onus is on the reader to verify that the information here is current.

Protocol

Customer

Machine No.

Device

Serial No

Control voltage [V~]

Power supply voltage [V~)

Field voltage [V=]

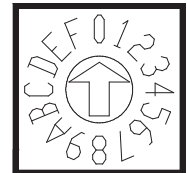
Inputs

Enable		contact ?	voltage [V=]
Command value		type	voltage [V=]
Command value, additional		type	voltage [V=]
Current command value I _{max2}		external	voltage [V=]

Speedcontroller settings

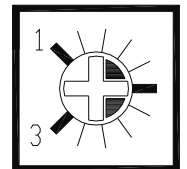
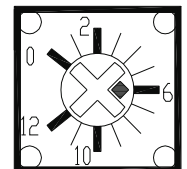
Switches

Tacho adjustment	S9	Position
P-term	S4	Position
I-term	S5	Position
D-term	S8	Position



Potentiometers

Speed	n _{max}	P4	Position
Peak current	I _{max1}	P5	Position
Peak current	I _{max2}	P6	Position
Continuous current	ID	P7	Position
Integrator	INT	P1	Position
Amplification	XP	P3	Position
IxR compensation		P2	Position



DIPswitches

ON	no.
OFF	no.

7 Protocol

Current controller settings

Switches

Switches S2	open	(off)
	closed(on)	
Switch S3, contact 1	60Hz	on	
	50Hz	off	

Measured data

Armature voltage	max.	[V=]
Armature current	peak	[A=]
Armature current	continuous	[A=]
DC tacho voltage	max.	[V=]
Tacho voltage	max.	[V=]
Acceleration	X4:16	[V/ms]
Integrator	X4:14	[V/ms]

Motor data

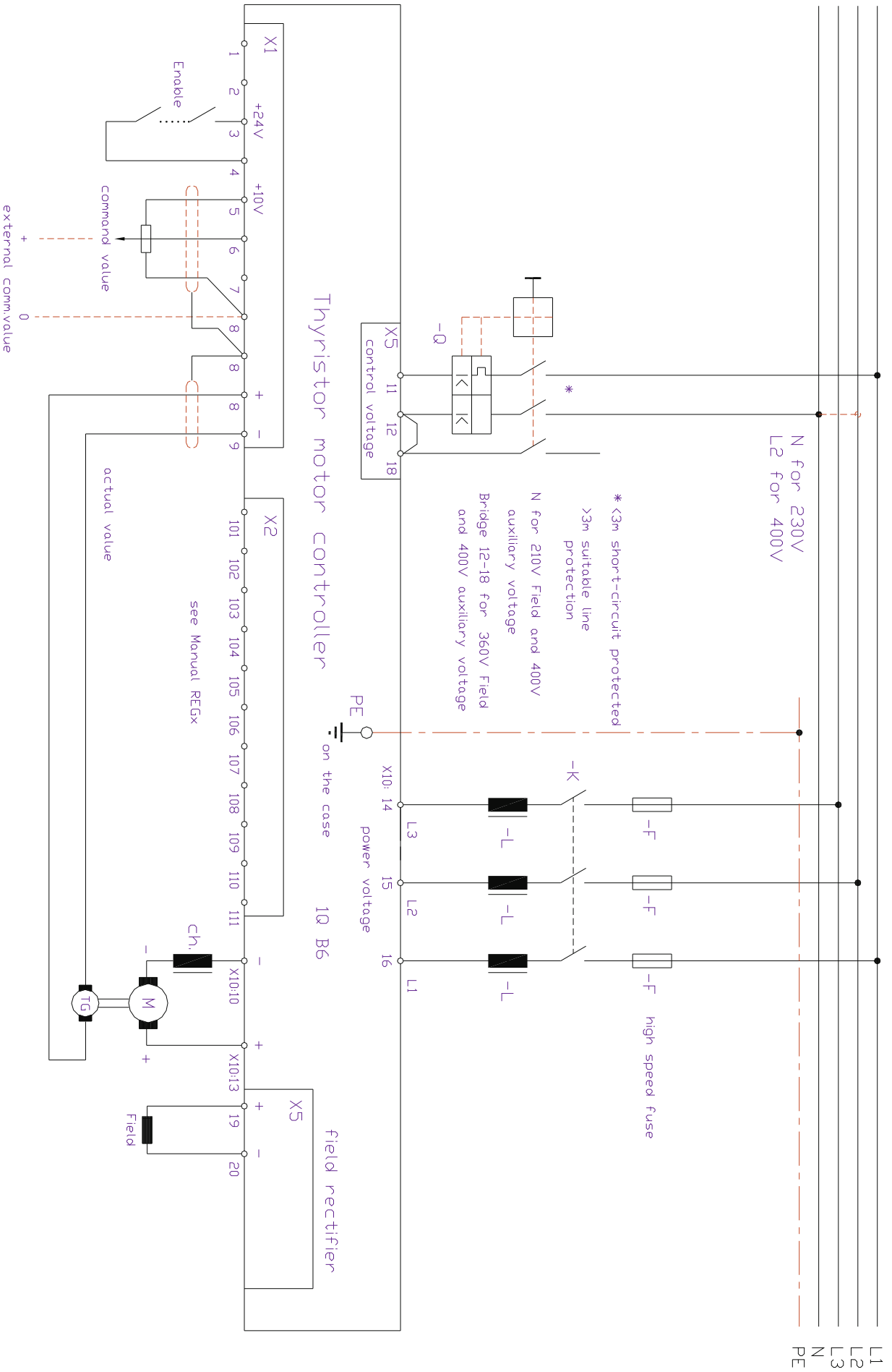
Type plate data

Manufacturer

Type Serial number

Motor voltage [V=] Motor current [A=]

Brake [V] Fan [V]



Connection Diagram

