

MANUAL

Classic Q3 15-150A

4 Quadrant

Thyristor Drive

Part 1 Thyristor Drive **Q3x/x-15-150A**

Part 2 **Analogue Control Electronics** **REGxx**



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Basic - Information

2 Basic - Information

2.1 Safety advice

Electronic equipment is not fault proof.

**Attention – High voltage
360-550V~, 450-550V=**
Shock hazard / Danger of life!!



Before installation or commissioning begins, this manual must be thoroughly read and understood by the technical staff involved.

The devices are electrical equipment (EB) to the power electronics for the control of power flow in electrical power systems.

Protection rating IP00.

**Control and power connections can
voltage lead, works without the drive!**

Measured before disassembly voltage!



2.2 Standards and guidelines:

The device and its associated components can only be installed and switched on where the local regulations and technical standards have been strictly adhered to:

EU Guidelines:	2004/108/EG, 2006/95/EG, 2006/42/EG EN 60204-1, EN292, EN50178, EN60439-1, EN61800-3, ECE-R100 ISO 6469, ISO 26262, ISO 16750, ISO 20653, ISO12100
IEC/UL:	IEC 61508, IEC364, IEC664, UL508C, UL840
VDE Regulations:	VDE100, VDE110, VDE160
Trade body guidelines:	VGB4

Basic - Information

The user must ensure that in the event of:

- device failure
- incorrect operation
- loss of regulation or control

the axis will be safely de-activated.



It must be ensured that the machines, equipment or vehicles are fitted with device independent monitoring and safety feature.

Non-earthed systems (e.g. vehicles) need to be secured isolation monitors.



There must be no danger to persons and property arising!

Assembly

- should only be carried out when all voltages have been removed and the units are secured
- should only be carried out by suitably trained personnel

Installation

- should only be carried out when all voltages have been removed and the units are secured
- should only be carried out by suitably trained personnel for electrics
- should only be carried in accordance with health and safety guidelines

Adjustments and programming

- should only be carried out by suitable trained personnel with knowledge in electronic drives and their software
- should only be carried out in accordance with the programming advice
- should only be carried in accordance with health and safety guidelines

CE

When mounting the units into machines and installations the proper operating of the units may not be started until it is ensured that the machine, the installation, or the vehicle comply with the regulations of the EC machinery directive 2006/42/EG and the EMC guideline 2004/108/EG.

On the installation and test conditions described in the chapter CE-advice it is adhered to the EC guideline 2004/108/EG including the EMC standards EN61000-2 and EN61000-4.

A manufacturer's declaration can be requested.

The manufacturer of the machine or installation is responsible for observing the threshold values demanded by the EMC laws.

QS

The devices are archived with serial number and the test data from the manufacturer for 5 years. The inspection reports may be requested.

Basic - Information

2.3 General and features

This manual describes the basic unit and
is only in connection with the manual of the control electronics
(e.g. REGxx) valid.



Manual use in connection with:

- an analogue control REGxx
- field regulation internal QS-F
- field regulation external F2xx
- options Multi-xx

Build

- switch cabinet mounting a
- according to the VDE, DIN and EU regulations
- standard control electronics REG
- intrinsically safe power section with current control loop
- controlled or uncontrolled field supply unit
- optional units

Galvanic isolation between

- the power section and the housing
- the power section and the control electronics

The distance of air gaps and leakage paths adhere to the VDE standards (>8mm).

Components

- fully insulated thyristor modules, comfortably over-dimensioned
- only components customary in trade and industrially standardized are used
- high-quality bases for the IC with external connections
- LED displays
- precision potentiometers for fine adjustments
- plug-in jumpers for the system set-up

Basic - Information

Characteristics

- * Series Classic Q3
- * Thyristor drive for dc motors
- * Power range 6.75kW to 1.1MW
- * Drive and brake in all 4 quadrants
- * Energy recovery
- * Intrinsically safe power section
- * Fast analogue current control
- * Temperature watchdog - power section
- * Circular current-free dual bridge circuit
- * Controlled or uncontrolled field rectifier
- * 26-pin interface
- * Features of the control electronics:
see Manual REGxx or third-party product documentation
- * Optional units

Basic - Information

2.4 Technical Data

Q3 400/450-x

Power connection: 360 ... 440V~
 Auxiliary voltage connection: 360 ... 440V~, 200 ... 250V~ or option
 Output voltage: max. ± 450V=
 Cooling: self cooling

Q3 400/450 -			15	25	40
Input current		A~	12	20	32
Output current	-peak 5s	A=	30	50	80
	-continous	A=	15	25	40
Elec. power		kW	6,75	11,25	18
Fuses		ff			
	-input 3 St	Aff	20	30	50
	-output 2 St	Aff	25	50	63
	-field	Af	10	10	10
Power chokes		Type	KD2-16	KD2,5-25	KD2,5-50
		mH	0,9	0,7	0,4
Armature chokes		Type	EI135A-16	EI135B-24	EI150B-35
		mH	33	16	8
Dimensions W x H x D		mm	290x230x190	290x230x190	290x230x190
Weight		kg	7,7	7,7	7,7

Q3 500/550-x

Power connection: 450 ... 550V~
 Auxiliary voltage connection: 360 ... 440V~, 200 ... 250V~ or option
 Output voltage: max. ± 550V=
 Cooling: self cooling

Q3 500/550 -			15	25	40
Input current		A~	12	20	32
Output current	- peak 5s	A=	30	50	80
	- continous	A=	15	25	40
Elec. power		kW	8,25	13,75	22
Fuses		ff			
	-input 3 St	Aff	20	30	50
	-output 2 St	Aff	25	50	63
	-field	Af	10	10	10
Power chokes		Type	KD2-16	KD2,5-25	KD2,5-50
		mH	0,9	0,7	0,4
Armature chokes		Type	EI135A-16	EI135B-24	EI150B-35
		mH	33	16	8
Dimensions W x H x D		mm	290x230x190	290x230x190	290x230x190
Weight		kg			

Basic - Information

Q3 400/450-x

Power connection: 360 ... 440V~
 Auxiliary voltage connection: 360 ... 440V~, 200 ... 250V~ or option
 Output voltage: max. ± 450V=
 Cooling: self cooling / 120-150A: ventilation fan

Q3 400/450 -			60	120	150
Input current	A~		48	96	120
Output current	-peak 5s	A=	120	240	300
	-continous	A=	60	120	150
Elec. power	kW		27	54	67,5
Fuses	-input 3 St	ff			
	-output 2 St	Aff	80	120	150
	-field	Aff	100	150	200
		Af	10	10	10
Power chokes		Type	KD3-75	KD4-100	KD4-150
		mH	0,3	0,25	0,16
Armature chokes		Type	EI150A-50	UI150B-100	UI180B-150
		mH	4	2,2	4,2
Dimensions W x H x D		mm	290x230x230	290x270x230	290x270x230
Weight		kg	7,7	8,6	13,5

Q3 500/550-x

Power connection: 450 ... 550V~
 Auxiliary voltage connection: 360 ... 440V~, 200 ... 250V~ or option
 Output voltage: max. ± 550V=
 Cooling: self cooling / 120-150A: ventilation fan

Q3 500/550 -			60	120	150
Input current	A~		48	96	120
Output current	- peak 5s	A=	120	240	300
	- continous	A=	60	120	150
Elec. power	kW		33	66	82,5
Fuses	-input 3 St	ff			
	-output 2 St	Aff	80	120	150
	- field	Aff	100	150	200
		Af	10	10	10
Power chokes		Type	KD3-75	KD4-100	KD4-150
		mH	0,3	0,25	0,16
Armature chokes		Type	EI150A-50	UI150B-100	UI180B-150
		mH	4	2,2	4,2
Dimensions		mm	290x230x230	290x270x230	290x270x230
Weight		kg	7,7	8,6	13,5

Basic - Information

2.5 Specification

Specification

Mains frequency	50 or 60Hz ±5%
Protection rating	IP 00
Format	VDE 0100 Group C / VDE 0160
Humidity rating	class F nach DIN 40040
Site of installation	< 1000m above sea level
Operating temperature range	0 ... 45°C
Extended operating temp. range	up to 60°C red. 2%/ $^{\circ}$ C
Storage temperature range	-30°C to + 80°C

Amplification

Input-Signal	0... ± 10V=
Output	0... ± 200% Type current

Enable

> + 10 Volt

Current control loop circuit

Control precision	± 2%
Control range	1:50
Over-current limiting	10 Sec. 200 % Type current

Speed control loop (see MANUAL REG)

Control precision (without actual value error)	± 0.1%
Control range	> 1:300

2.6 Interface

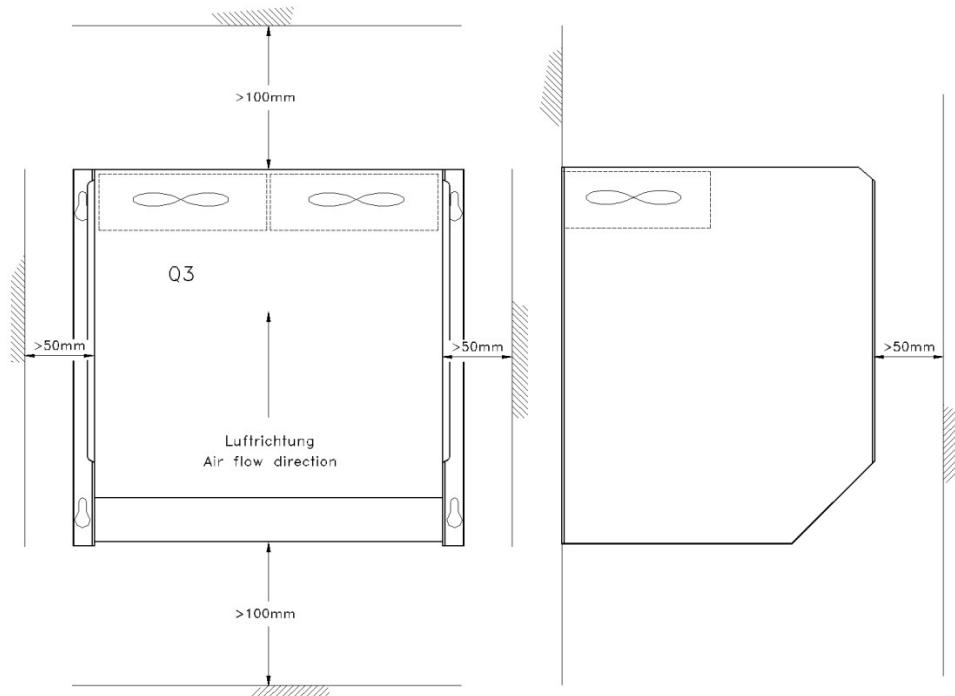
Interface control electronics X3

Function		Connector no.
+ 24V	±10%	X3: 1 and 2
+ 15V	±2%	X3: 3 and 4
- 24V	±10%	X3: 5 and 6
- 15V	±2%	X3: 7 and 8
Device GND	0	X3: 9, 10, 11, 12, 13, 14
I-command value (GND)	0	X3: 15
I-command value (signal)	+10V=	X3: 16
Current controller enable	+10V=	X3: 17
Drive disable1	+10V=	X3: 18
Drive disable 2	+10V=	X3: 19
N (speed) actual	+10V=	X3: 20
I (current) actual	±5V=	X3: 21
Over-current power section	+10V=	X3: 22
Option UA	±10V=	X3: 23
Option UA	0 - +10V=	X3: 24
Drive ready BTB	+10V=	X3: 25
	+5V	X3: 26

Mechanical installation

3 Mechanical installation

3.1 Mounting



Q3-Montage-V616

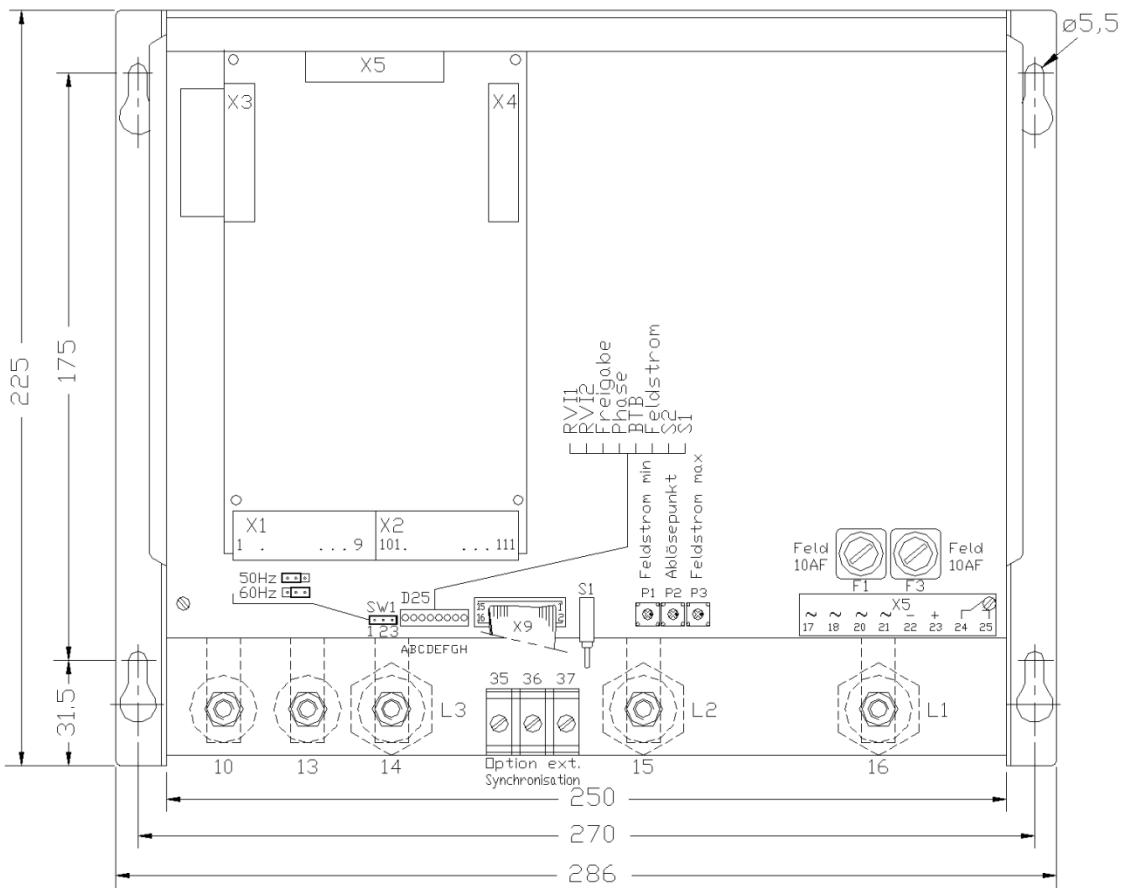
Ambient temperature 0 to <45°C (reduced, up to 60°C)
Max. cooling unit-temperature 80°C

Air-mass throughput 15-60A natural convection
120A 360m³h
150A 360m³h

Dissipation loss with max. power			
Unit Q3-x/X	Unit W	Fuse	Mains choke W
15	65	32	30
25	95	42	40
40	140	65	60
60	200	100	75
120	380	140	125
150	470	160	185

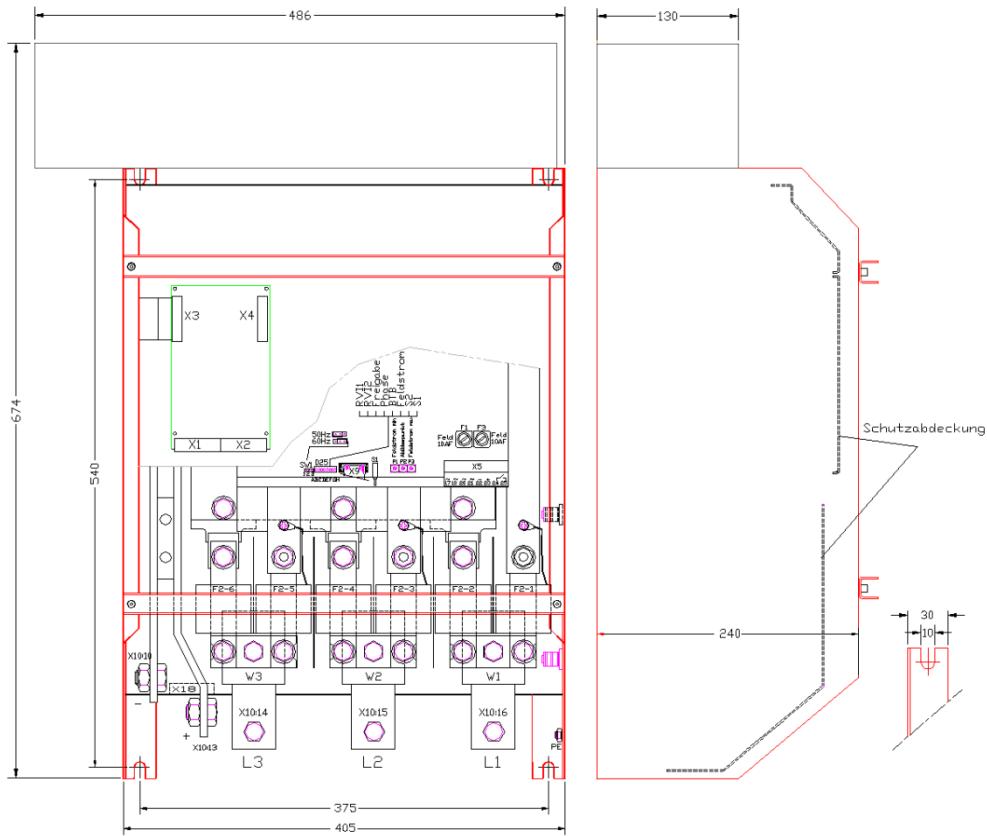
Mechanical installation

3.2 Dimensions Q3 15-60A



Mechanical installation

3.3 Dimensions Q3 120-150A

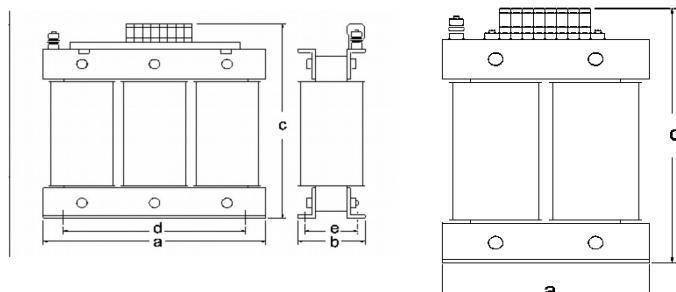


E-Q3-M657-Maßbild840

Dimensions					
Unit Q3-x/x	Width	Height	Depth	Drill hole	Weight
	mm	mm	mm	mm	
15A	286	225	190	279x175	7.7
25	286	225	190	279x175	7.7
40	286	225	190	279x175	7.7
60	286	225	230	279x175	10.5
120	286	270	230	279x220	13.5
150	286	270	230	279x220	13.5

Mechanical installation

3.4 Three-phase power-choke



Q3-V257-UID-Trafo und Q3-V256-UI-Trafo

Features	
UN	400V~50/60Hz
UK	4%
Protection rating	IP00
Isolation class	T40/E
Vertical angle bracket	

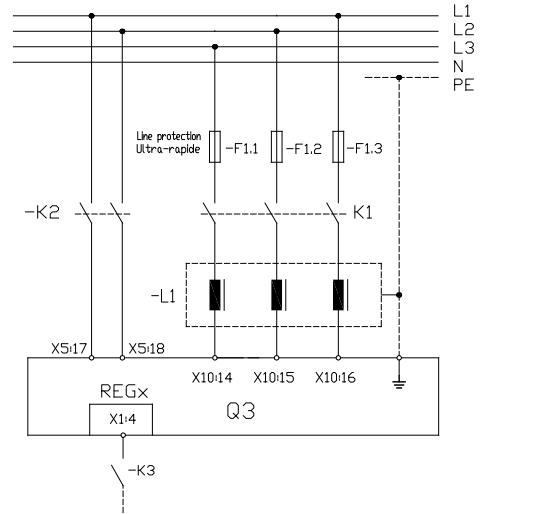
Q3-x/x-	Choke type	L mH	PV W	Dimension					Weight	Screw
				a	b	c	d	e		
15	KD2-16	1.7	30	100	55	115	56	44	2	4
25	KD2.5-25	1.0	40	150	75	150	90	55	3.5	5
40	KD2.5-50	0.6	75	150	90	150	90	70	5.1	5
60	KD3-75	0.4	110	185	135	170	122	85	7	6
120	KD4-100	0.3	125	240	130	225	140	85	14.5	6
150	KD4-150	0.2	185	240	150	225	140	105	15.5	6

with filter: KDFxx

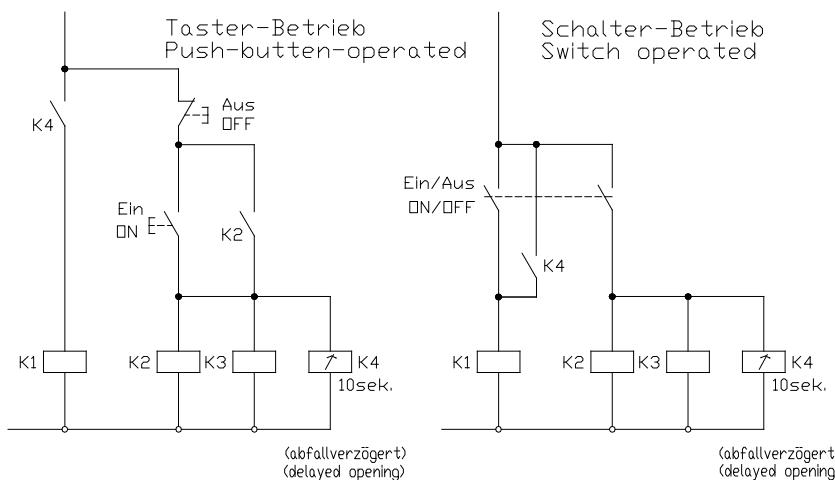
Electrical installation

4 Electrical installation

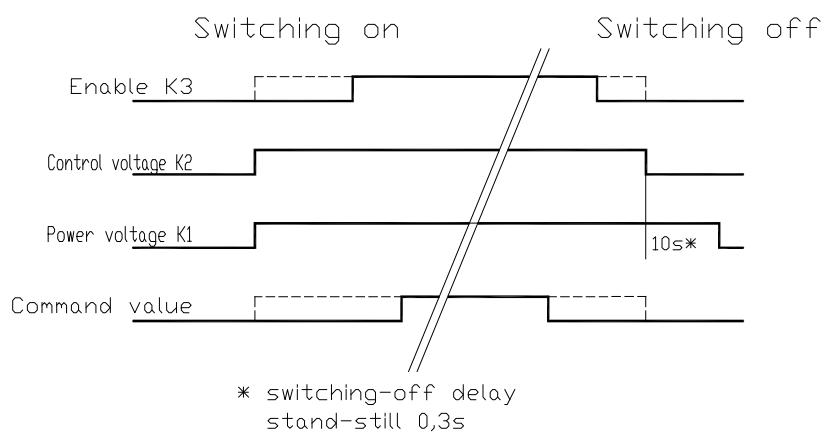
4.1 Connections



E-Q3-647



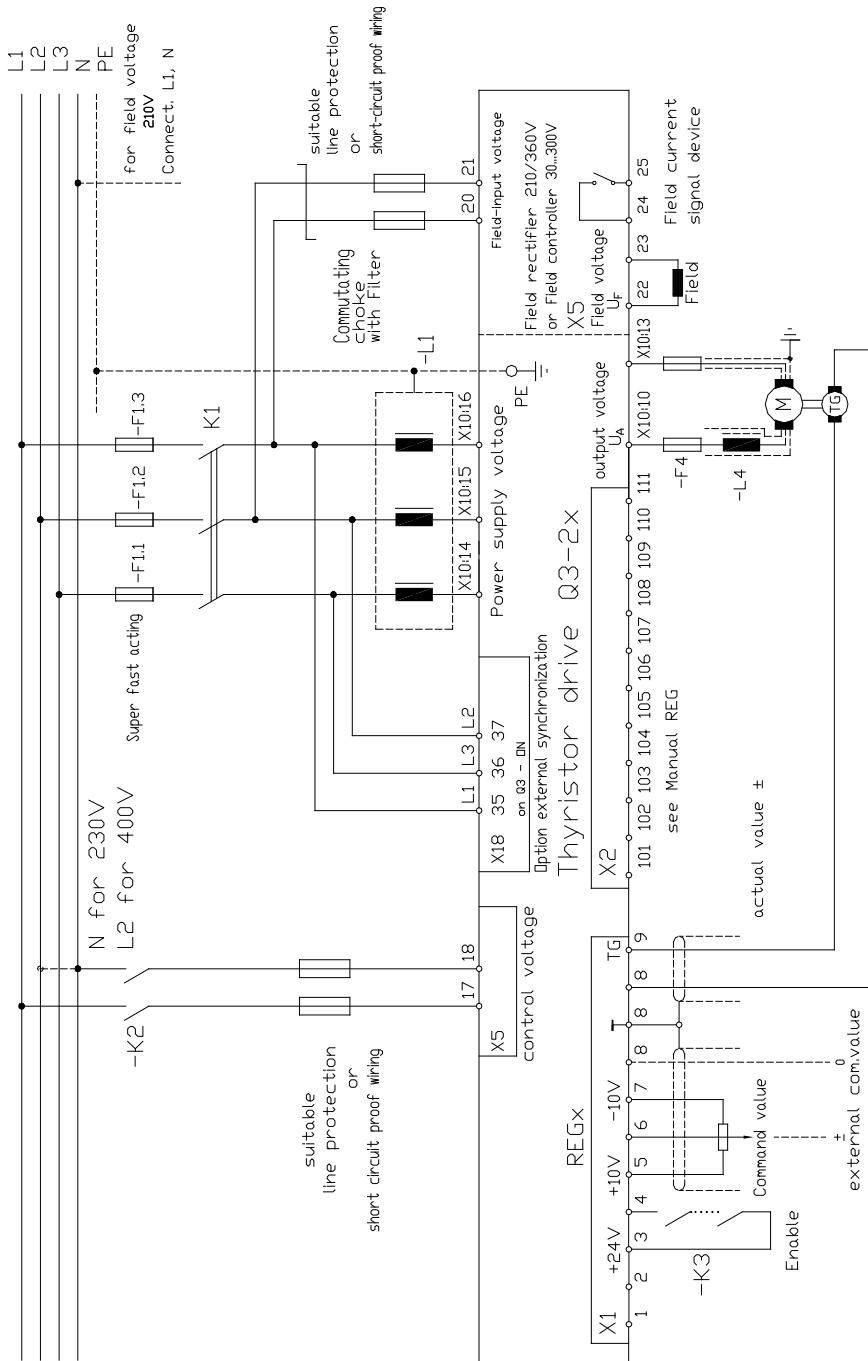
Q3-Relais-1V647



E-Q3-Schaltfolge-1-V647

Electrical installation

4.2 Connection diagram



For EMC: All control lines have to be shielded
Motor and field lines have to be shielded

Electrical installation

4.3 CE-Advice

The devices adhere to the EU guidelines 89/336/EWG and the technical standards EN 61000-2 and 61000-4 provided that the following conditions are observed:

- The device, transformer and filter capacitors are mounted on a 800x800x2mm mounting plate
- The mounting plate must be connected to ground using a 10mm² wire.
- The motor housing must be connected to ground using a 10mm² wire.
- The device ground X1:8 must be connected to the mounting plate using a 2.5mm² wire.
- Device PE screw must be connected to the mounting plate using a 4mm² wire, l = 50mm.

Three-phase connection:

Power choke type: see technical details

Filter capacitors: 0.5mF/600V~ 3 x 1µF (x) + 1 x 1µF (y)

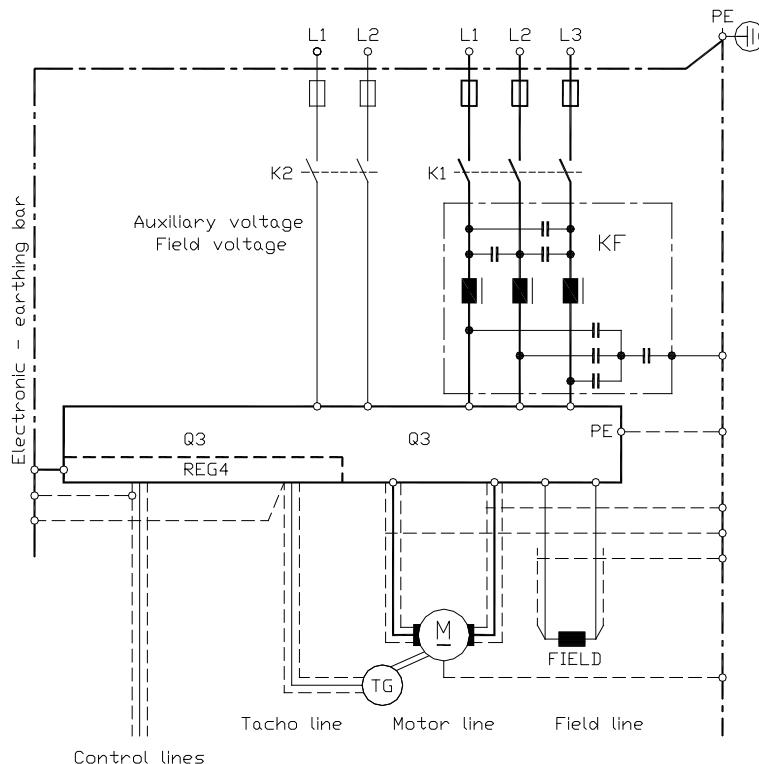
Conductor length between the device and the power choke <250mm

Motor connection:

Motor conductors l = 1.5m, shielded

Tacho and all control lines l = 1.5m, shielded

Shielding connected to PE



KF = Commutation choke with filter capacitor

E-Q3-A639

Electrical installation

4.4 Connection advice

Attention:

The order of the connections to the connector numbers or screw terminals is obligatory. All further advice is non-obligatory.

The input and output conductors may be altered or supplemented in accordance with the electrical standards.

Note:

- Connection and operating instructions
- Local regulations
- EU guideline 89/392/EWG
- VDE and TÜV regulations and Trade body guidelines

Switch on the auxiliary voltage and the supply voltage simultaneously.

Switch off the supply voltage after the auxiliary voltage

Input filter

see CE advice

Short conductor length to be used between the input filter and the device

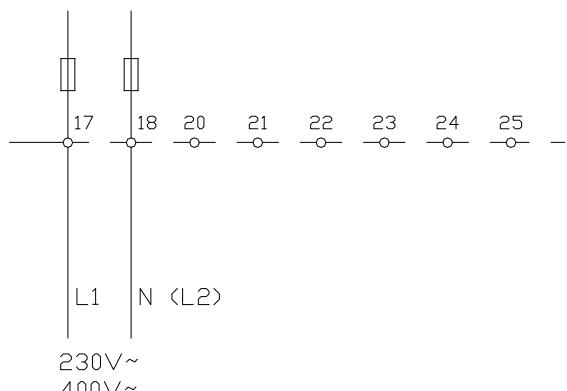
Auxiliary voltage connection

Connection	terminal X5:17, X5:18
Power supply	400V~ ±15%
Special voltages	24V~, 110V~, 230V~, 500V~
Input current	max. 300mA
Phase position	regardless
Internal fuses	FE1, FE2 0.8AT

Min. line cross-section 0.5mm²

External fuse

Min. line protection 6A



Note: Observe the respective type plate. Control voltage XXX

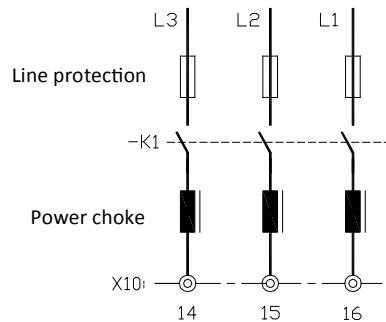


Electrical installation

4.5 Power connection

Direct power connection

Phase	L1	Bolt X10:16
Phase	L2	Bolt X10:15
Phase	L3	Bolt X10:14



Note:

L1, L2, L3 – clockwise rotating field

Protecting earth – PE connection

Unit Q3 x/x- Type current	Power choke KD-three-phase current K-Phase choke	Fuses A Superfast acting installed
240	KD5-250	6 x 250 A FF
360	K170-400	6 x 315 A FF
480	KU150-600	6 x 400 A FF
840	KU150-800	6 x 500 A FF

Power connection with an auto-transformer

1.1 x continuous motor power

Secondary voltage

0.9 x Motor voltage

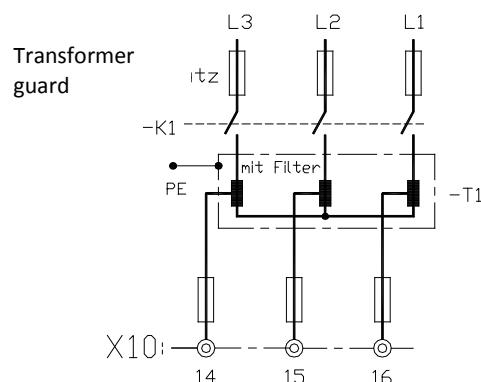
Transformer fuses

Slow acting

Observe the switch –on current!

Nput fuses F1, F2, F3

Rf. to the table above



Q3-V747-with filter

Attention:

If the secondary voltages produced by the transformer are inferior to 60% the voltage watchdog has to be adapted. These modifications may only be effected in the factory and thus, the voltages have to be indicated on order.

Watchdog connection

LED BTB inactive

- >>> missing phase
- >>> wrong rotating field

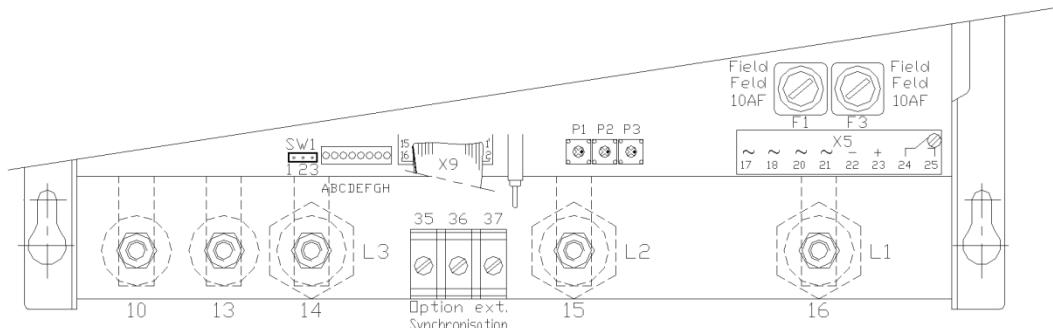


Electrical installation

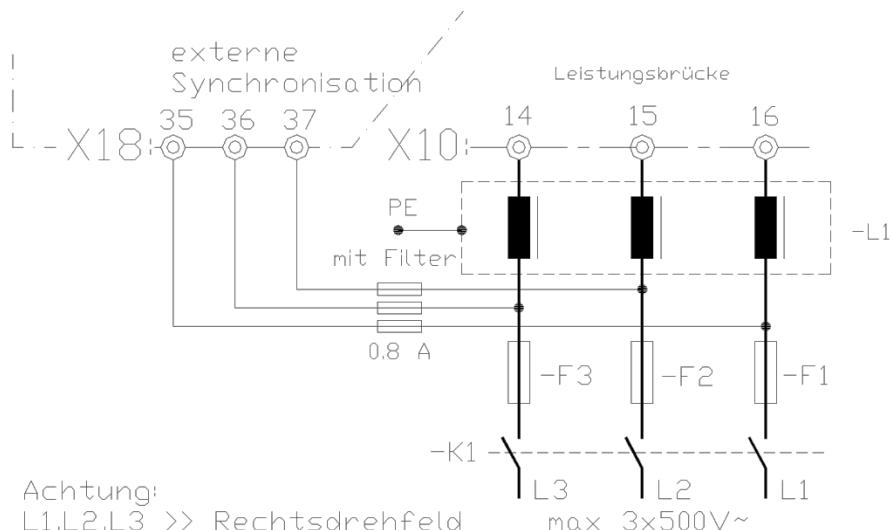
4.6 Option – external synchronization

For special applications it might be necessary to tap the synchronization before the power commutating choke, e.g.

- when operating via field triggering circuit
- in case of an instable power supply



Q3-M656-ext-synch-15-40



Q3-ext-synch-an schluss-v647

The wiring has to be short-circuit proof or protected means of a line protection.

Connection across the terminals X18:35, 36, 37

Observe the phase position!

- L3 across X10:14 (via power choke) and directly across terminal X18:36
- L2 across X10:15 (via power choke) and directly across terminal X18:37
- L1 across X10:16 (via power choke) and directly across terminal X18:35

Attention:

If incorrectly connected at X18 – the device can be destroyed



Electrical installation

4.7 Motor-connection

Positive command value		
Motor – bolt	bolt	X10:13 X10:10
Attention:		
Armature choke only for a few applications: Inductance: $L [mH] = U_A / I_A \times 0,8$ Standard version without a choke motor lines have to be shielded		<p>Q3-Motor-V647-1</p>

Unit Q3 x/x- Type current	Power choke* Direct current	Fuses A super fast actin F4	Min. conductor cross-section (mm ²)
15	EI135A-16	2 x 25	1.5
25	EI35B-24	2 x 35	2.5
40	EI150B-35	2 x 63	4
60	EI150A-50	2 x 100	10
120	UI150B-100	2 x 150	25
150	UI180B-150	2 x 200	35

*choke are necessary only for special applications

Switching in the armature circuit

- dc circuit current-free
- disable inactive

Warning:

Faulty switching will create arcing across the switch contacts.



Power supply failure - brake resistor

Break contact of the mains contactor K1

Rating:

Resistor RNB = max. armature voltage/2 x type current

Braking effect only with an excited field!



Attention:

Power lines have to be shielded and routed separately from control lines!

For electro-magnetic interferences please refer to the CE advice.

Electrical installation

4.8 Field-connection

Constant field

Connection	Plug-in terminal connectors
Input	X5:20, X5:21
Field	negative X5:22
Field	positive X5:23
Signal contact	X5:24, X5:25

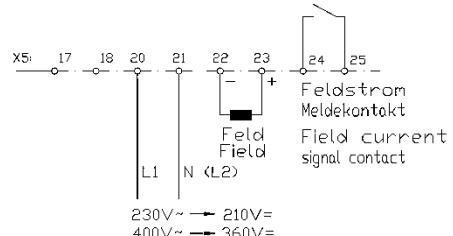
Field voltage

Power supply	Field supply
230V~	210V=
400V~	360V=
variable	0.9 x transformer secondary voltage with auto-transformer

Field current	max. 10A=
Internal fuses	2 x 10AF
Cross-section/connect line	min. 0.5mm ²
External protection	line protection, mind. 6A

Field current watchdog

Operating current	see table
Signal contact	48V/0.5A
Connection	X5:24, X5:25
Error	open contact



Q3-Feld-1-V647-220V

Rate current Q3	Operating current Field current watchdog
15 A	120 mA
24 A	130 mA
40 A	140 mA
60 A	180 mA
120 A	330 mA
150 A	650 mA

Electrical installation

Field-connection

Control field

Optional field current controller Q3-F
Observe Manual Q3-F

Field current control
Field voltage max. 320V=
Control range 200mA to 10A

Combination of field/armature control

Field triggering circuit
Internal potential-free armature voltage measuring
Field voltage max. 320V=
Control range 200mA to 10A
Triggering point UA max. 450V=
Adjustments min./max. field current control parameter

EMC: for a controlled field >>> use shielded field lines



Attention:

No switch contact, fuses etc. in DC - field circle

Electrical installation

4.9 Actual value

Actual value connection

Tacho

Suitable actual value encoders: tacho generator
Brushless tacho generator with evaluation electronics
Incremental encoders with evaluation electronics

Note:

AC or three-phase tachos with rectification are not suitable



Connection

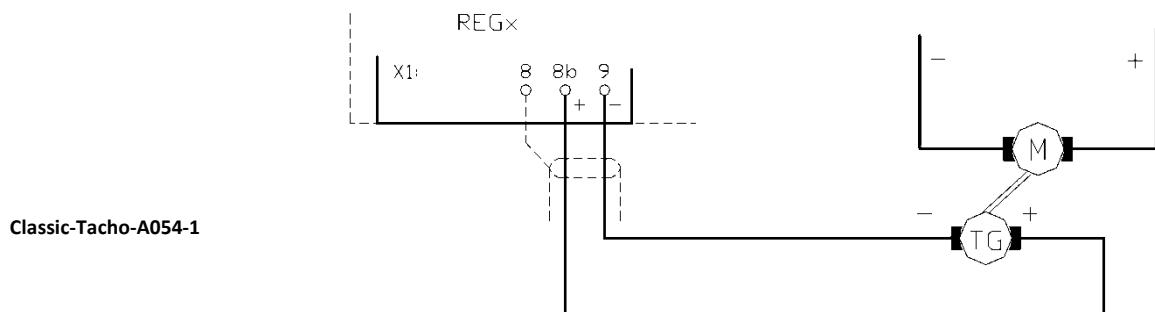
Control electronics (see Manual REG)

In case of a positive command value

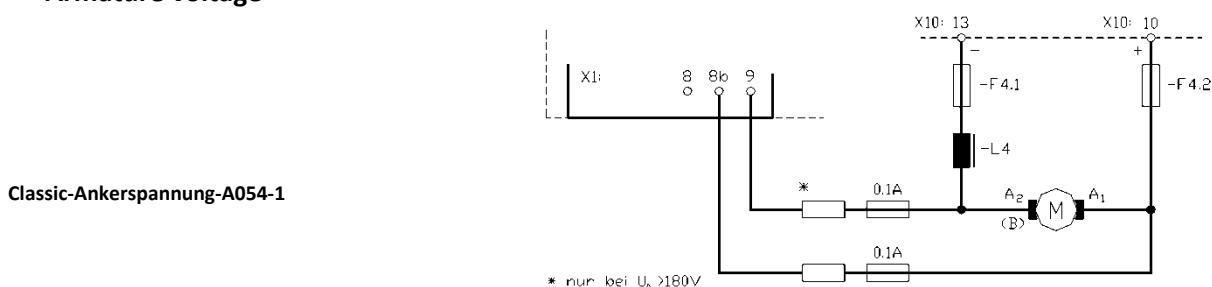
Tacho positive X 1:8b

Tacho negative X 1:9

Shield X 1:8



Armature voltage



Ground referenced actual value

Fuses 2x 0.1A directly in the armature circuit

For armature voltage $> 180V$ = additional resistors are required

Use unit EXZU-UA1

Note: Observe MANUAL REGxx

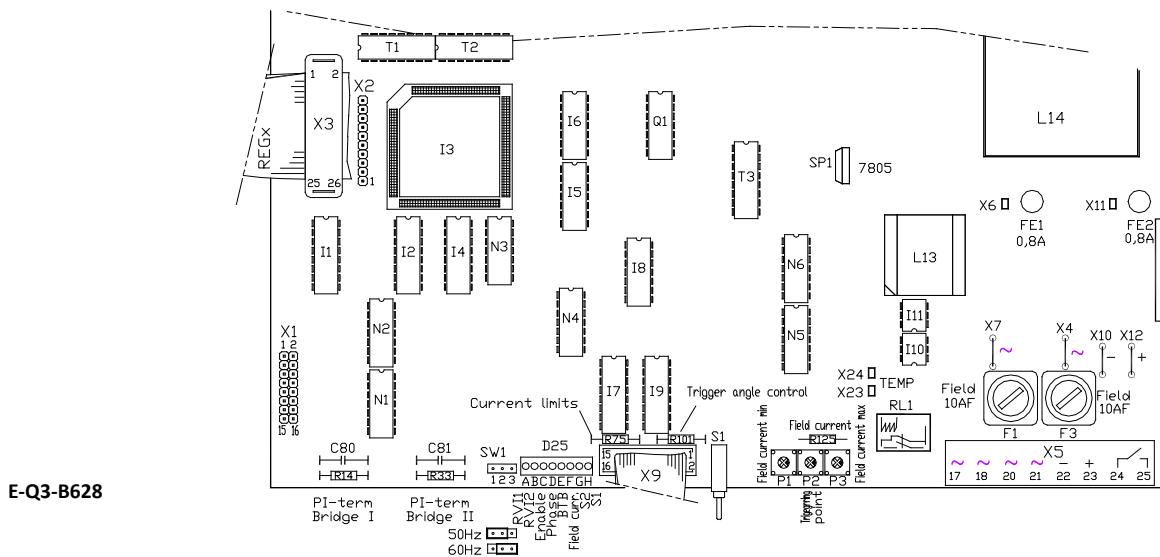
Option: In case of internal potential-free armature voltage control please indicate on order.



Adjustments

5 Adjustments

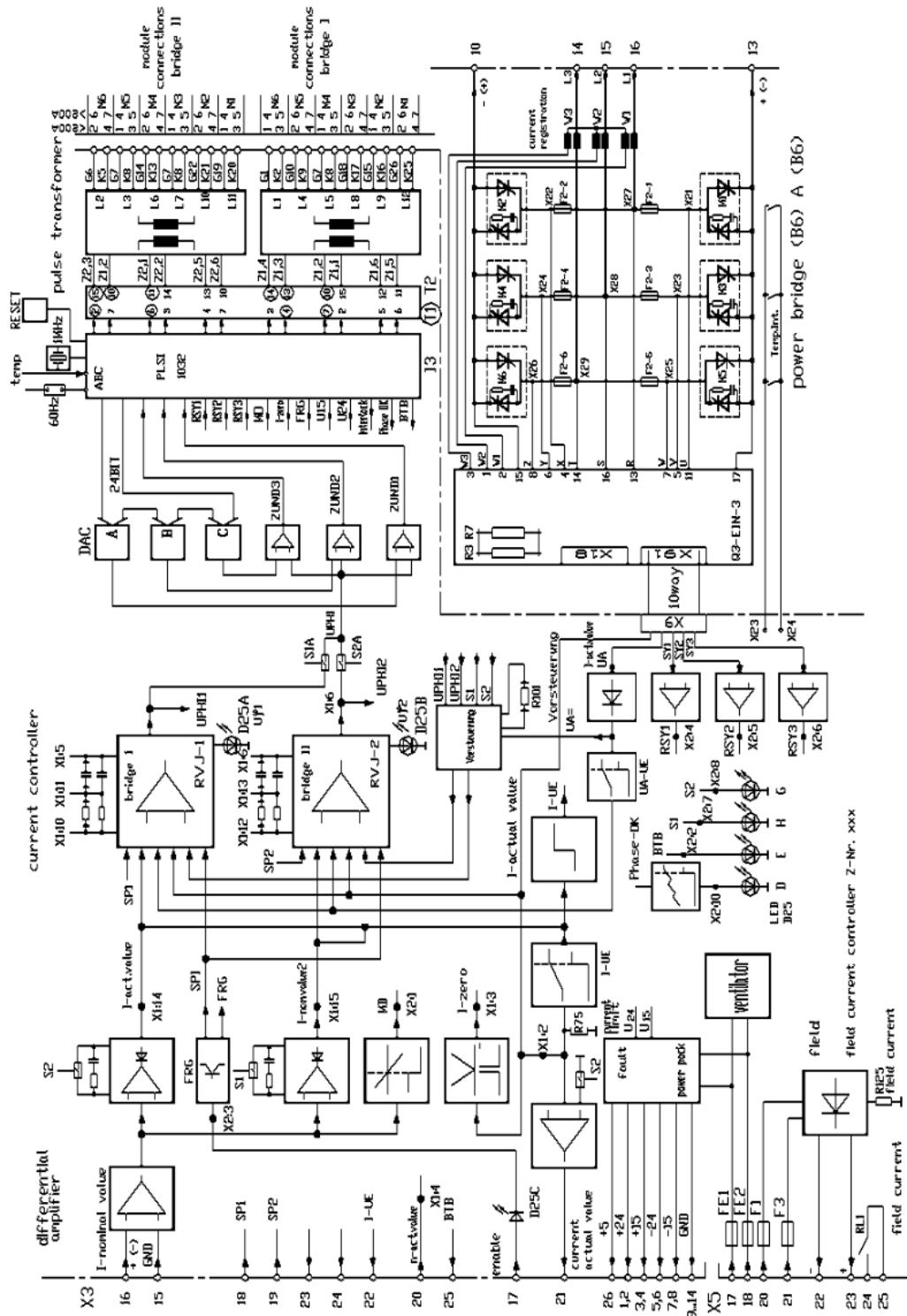
5.1 Components



Variable elements	Function	Range
R14	P-amplification current controller 1	18kΩ to 470kΩ
R33	P-amplification current controller 2	18kΩ to 470kΩ
R75	Exact adjustment current limit	100kΩ to 470kΩ
R101	Trigger angle control	240kΩ to 560kΩ
R125	Field current	
C80	Integral term - current controller 1	0.1μF to 2.2μF
C81	Integral term - current controller 2	0.1μF to 2.2μF
Potentiometer		
P1	min. field current	0 to 15%
P2	Triggering point for armature/field control	200 to 450V
P3	max. field current	0 to 100%
Jumper		
SW1 Pos.1-2	50Hz adjustment	
SW1 Pos.2-3	60Hz adjustment	
Switch		
S1	Reset	
LED displays		
D25A	Current control loop RVI-1	control active
D25B	Current control loop RVI-2	control active
D25C	Enable current controller/triggering	enabled
D25D	Phase error	error
D25E	BTB ready	operational
D25F	Field current	luminous intensity = field current (only for a controlled field)
D25G	Current flow direction S2	active
D25H	Current flow direction S1	active

Adjustments

5.2 Circuit diagram



E-Q3-S654

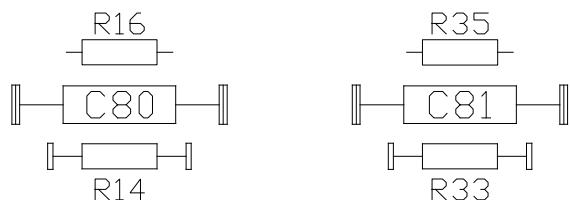
Adjustments

5.3 Current controller

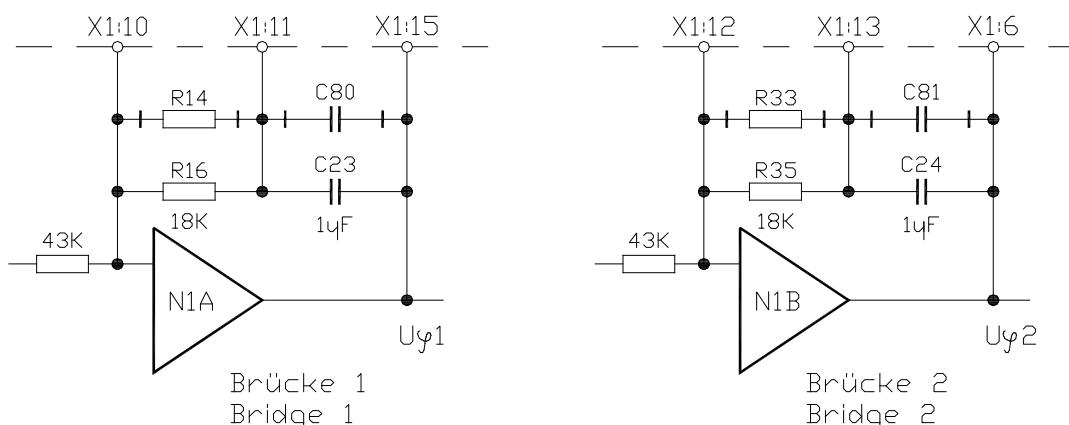
Current controller – PI loop circuit

Bridge 1 negative
Bridge 2 positive

R14, C80
R33, C81



Q3-Strom-PI-pos-V647-1



Q3-Strom-P1-1-V647

Basic set-up

Amplification ~0.4

Changing the amplification

Integration time ~18ms

Bridge 1	Bridge 2
$18k\Omega \times R14$ $X_p = \frac{18k\Omega + R14}{43k\Omega}$	$18k\Omega \times R33$ $X_p = \frac{18k\Omega + R33}{43k\Omega}$

Changing the integration time

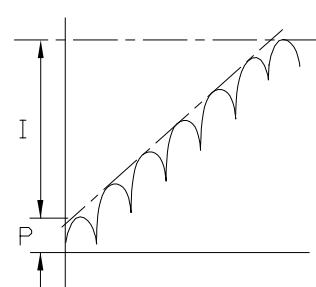
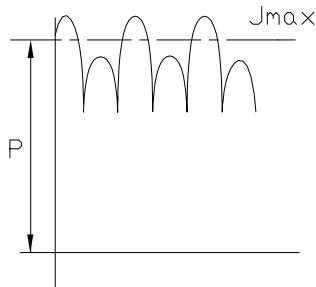
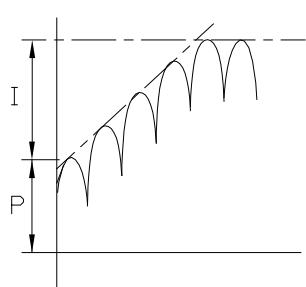
Bridge 1	Bridge 2
$\tau[mm] = \frac{18k\Omega \times R14}{18k\Omega + R14} \times 1\mu F + C81$	$\tau[mm] = \frac{18k\Omega \times R33}{18k\Omega + R33} \times 1\mu F + C80$

Adjustments

Optimization of the current controller

- Connect an oscilloscope across the current actual value X3:21
- Current command value step-change $\pm 1V$ X3:16
- Increase the current command value by 1V steps to $\pm 10V$
- Alter the P-amplification by means of the resistors R14 and R33
- Optimal adjustment fig. 1
- Not permissible adjustment fig. 2
- Alter the integral part by means of the capacitors C80 and C81

Oscilloscope – current adjustment



Q3-strom-PF-QS2T-1-V161

graphic 1
setting optimal

graphic 2
amplifier too high

graphic 3
P-amplifier small

Note:

Any changes in the optimization of the current controller must be checked by means of an oscilloscope.



Adjustments

5.4 Displays

BTB signal - Drive ready

BTB signal X3:25 >+5V

Error X3:25 <+5V

Error

Voltage error 24V, 15V, 5V saved

Phase error, rotating field saved

Defective input fuse saved

Over-temperature saved

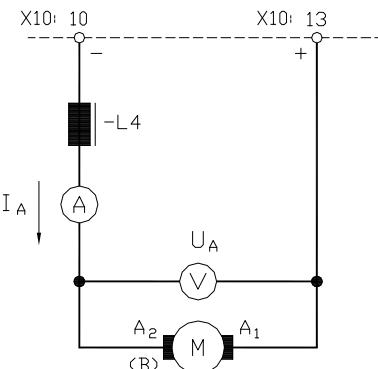
In case of errors or failure the power section is immediately internally disabled without delay.
To clear the saved error re-enable the drive (switch off/on or reset key)

Measurements

Measurement advice

Measuring instruments: multi-meter for current and voltage shunt or clamp-on ammeter

Measuring faults: mean value > actual value
acc. to the form factor
approx. 1 to 5%



Measured values

with a positive command value

Q3-Motor-Mess-1V647

Voltage: X10:10 positive X10:13 negative
max 1.15 x power supply
For 400V~ >> 460V=

Current: ammeter in the motor circuit
5s 200%, continuously 110% type current



Measured values across REGxx (selectable, see Manual REGxx)

Speed X2:109 ±5V or ±10V for ±100% speed
Current X2:111 ±5V or ±10V for ±200% current

GND X2:104

Commissioning

6 Commissioning

6.1 Commissioning Q3 x/x-x with REG4

Check the following connections before commissioning

Observe the type plate!



Basic connection - power connections Q3

Power supply	power	bolts X10:14, X10:15, X10:16
Power supply	auxiliary voltage	terminals X5:17, X5:18
Power supply	field	terminals X5:20, X5:21
Motor connection	A1/A2	bolts X10:10, X10:13
Field connection	F1/F2	terminals X5:22, X5:23
Field current signal		terminals X5:24, X5:25
Protecting earth	PE	earthing screws PE on the housing

Control connections

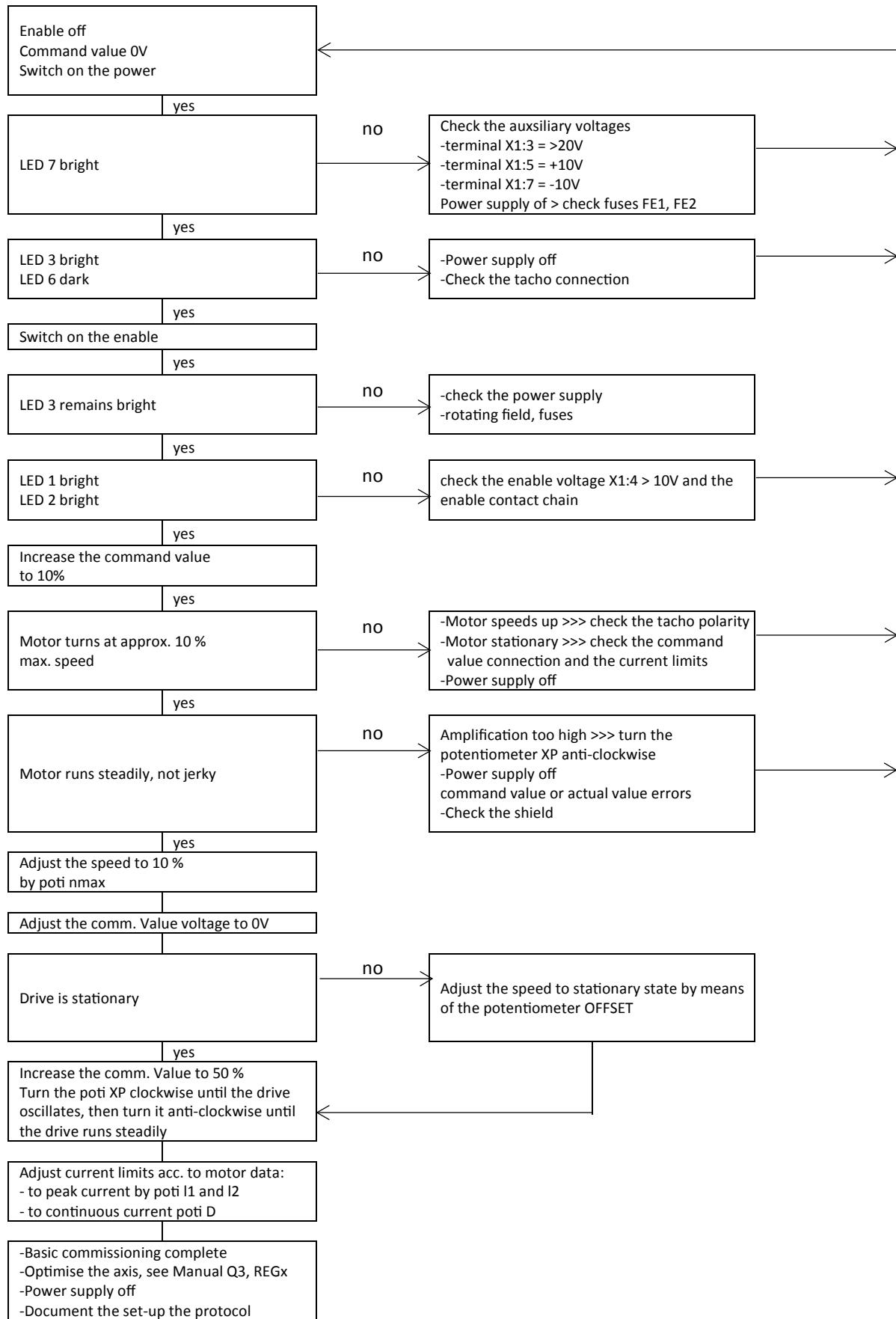
Enable	contact between X1:3 and X1:4
Command value	signal X1:6, GND X1:8a
Actual value	signal X1:9, GND X1:8b
Shields	X1:8

Control electronics REG4

Switch	S4	PI amplification	position 4
Switch	S5	I-term	position 4
Switch	S8	D amplification	position 8
Switch	S9	actual value	position 8
Potentiometer	I1	peak current	10%
Potentiometer	I2	peak current	10%
Potentiometer	ID	continuous current	100%
Potentiometer	XP	amplification	50%
Potentiometer	INT	integrator	left full scale
Potentiometer	nmax	speed	left full scale
Potentiometer	offset	offset	50%

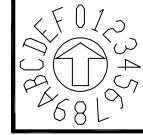
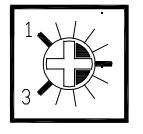
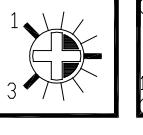
Commissioning

Commissioning Q3 x/x-x with REG4



Commissioning

6.2 Protocol Q3 x/x-x with REGxx

Customer				Machine no.		
Device				Serial no.		
Control voltage	[V~]					
Power supply voltage	[V~]					
Field voltage	[V=]					
Inputs						
Enable	Contact?	Voltage [V=]				
Command value	Type	Voltage [V=]				
Command value, additional	Type	Voltage [V=]				
Current command value	I _{max1} external	Voltage [V=]				
Current command value	I _{max2} external	Voltage [V=]				
Speed controller settings REGxx						
Switches						
Tacho adjustments	S9	Position		 REG5 - Schotax	1	
P-term	S4	Position				
I-term	S5	Position				
D-term	S8	Position				
Potentiometers						
Speed	n _{max}	P4	Position	 REG5 - Poti 1	2	
Peak current	I _{max1}	P5	Position			
Peak current	I _{max2}	P6	Position			
Continuous current	I _D	P7	Position			
Integrator	INT	P1	Position	 REG5 - Poti 2	3	
Amplification	X _p	P3	Position			
I _{xR} compensation		P2	Position			
DIP switch						
ON	No.					
OFF	No.					

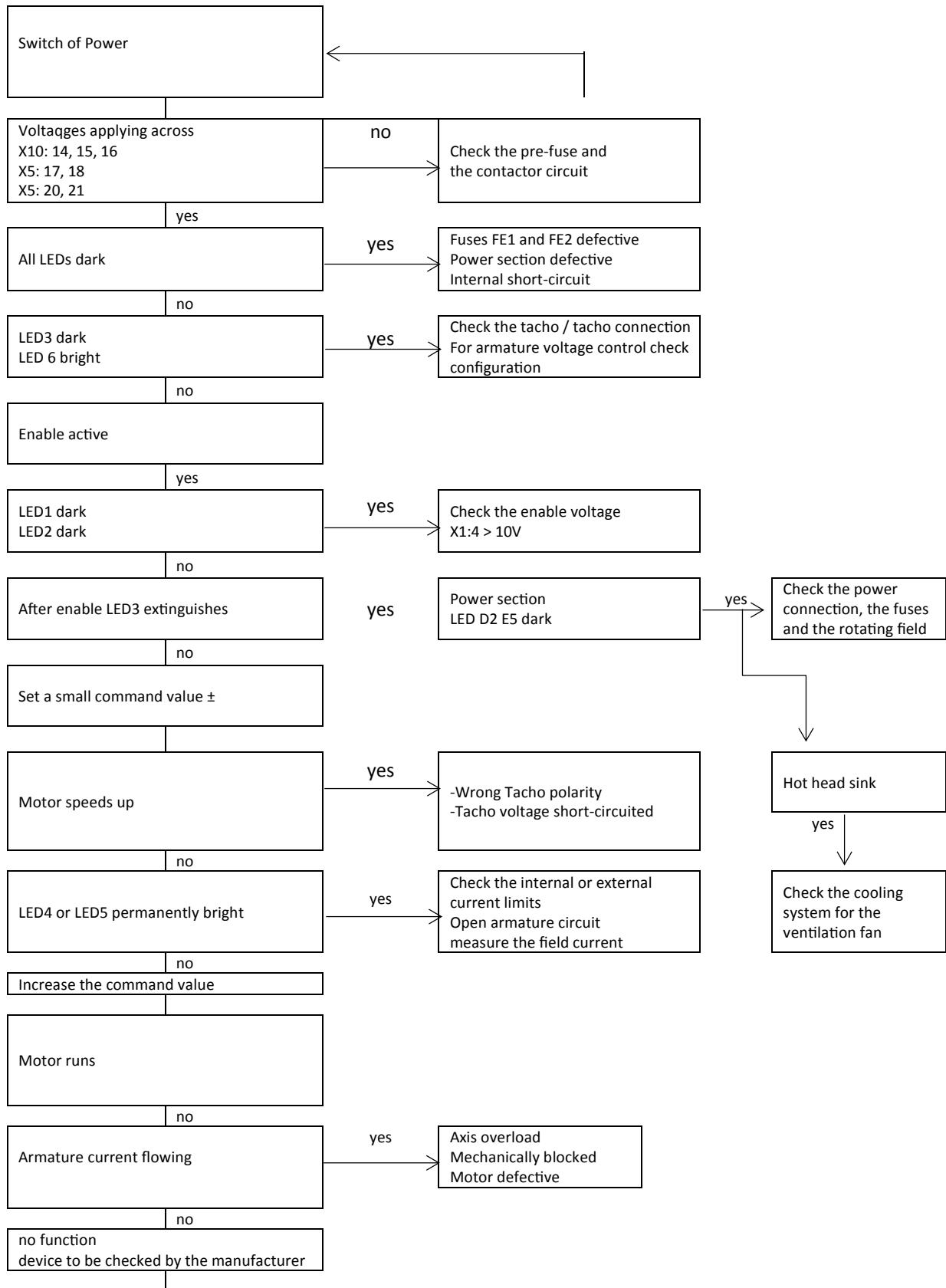
Commissioning

Current controller adjustments

Current controller settings			
P-amplification	R14=....	R13=....	
I-term	C80=....	C81=....	
50/60 Hz			
Jumper SW1	Pos. 1-2 (50Hz)	Pos. 2-3 (60Hz)	
Measured data			
Armature voltage	max.	[V=]	
Armature current	peak	[A=]	
Armature current	continuous	[A=]	
Tacho voltage	max.	[V=]	
Acceleration	X4:16	[V/ms]	
Integrator	X4:14	[V/ms]	
Motor data			
Type plate data			
Manufacturer			
Type		Serial no.	
Motor voltage [V=]		Motor current [A=]	
Field voltage [V=]		Field current [A=]	
Tacho voltage [V/min ⁻¹]		Tacho type	
Brake [V]		Fan [V]	
Nominal speed [rpm]			

7 Fauls

7.1 Fauls



Fauls

7.2 Error diagnosis

Error diagnosis	
Malfunction	Causes
Motor does not run	<ul style="list-style-type: none">-Wrong power supply and motor connections-Activated fuses-Missing enable or command value-Current limit too low-Missing BTB
Motor speeds up	<ul style="list-style-type: none">-Wrong polarity of the actual value (Tacho armature voltage)-Values of the tacho switch S9 too low-Command value too high <ul style="list-style-type: none">For armature voltage control-Field current too low-Fuses, armature voltage feedback activated
Motor runs unsteadily	<ul style="list-style-type: none">-Mechanical defect of the tacho-Tacho malfunction-Amplification on the speed controller too low or too high-Wrong PID parameter-Command value errors-Amplification of the current controller too low or too high
No motor torque	<ul style="list-style-type: none">-Current limits too low-Field current too low-Mechanical overload of the axis

Warranty

8 Warranty

8.1 Warranty

We guarantee that the device is free from material and production defects. Test results are recorded and archived with the serial number.

The guarantee time begins from the time the device is shipped, and lasts one year. WE undertakes no guarantee for devices which have been modified for special applications.

During the warranty period, we will, at its option, either repair or replace products that prove to be defective, this includes guaranteed functional attributes. We specifically disclaim the implied warranties or merchantability and fitness for a particular purpose. For warranty service or repair, this product must be returned to a service facility designated by us.

For products returned to us for warranty service, the Buyer shall prepay shipping charges to us and we shall pay shipping charges to return the product to the Buyer.

However, the Buyer shall pay all shipping charges, duties, and taxes for products returned to us from another country.

The foregoing warranty shall not apply to defects resulting from:

- * improper or inadequate repairs effected by the Buyer or a third party,
- * non-observance of the manual which is included in all consignments,
- * non-observance of the electrical standards and regulations
- * improper maintenance
- * acts of nature

All further claims on transformation, diminution, and replacement of any kind of damage, especially damage, which does not affect our device, cannot be considered. Follow-on damage within the machine or system, which may arise due to malfunction or defect in the device cannot be claimed.

This limitation does not affect the product liability laws as applied in the place of manufacture (i. e. Germany).

We reserve the right to change any information included in this MANUAL.

All connection circuitry described is meant for general information purposes and is not mandatory.

The local legal regulations, and those of the Standards Authorities have to be adhered to. We do not assume any liability, expressively or inherently, for the information contained in this MANUAL, for the functioning of the device or its suitability for any specific application.

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